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2002

<https://hdl.handle.net/10356/101616>

<https://doi.org/10.1017/S0022112002002173>

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Direct numerical simulation of a separated turbulent boundary layer

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(Received 21 February 2001 and in revised form 12 June 2002)

Direct numerical simulation of two turbulent boundary layer flows has been performed. The boundary layers are both subject to a strong adverse pressure gradient. In one case a separation bubble is created while in the other the boundary layer is everywhere attached. The data from the simulations are used to investigate scaling laws near the wall, a crucial concept in turbulence models. Theoretical work concerning the inner region in a boundary layer under an adverse pressure gradient is reviewed and extended to the case of separation. Excellent agreement between theory and data from the direct numerical simulation is found in the viscous sub-layer, while a qualitative agreement is obtained for the overlap region.

1. Introduction

The separation of boundary layer flow is of crucial importance in many applications, including airfoils, road vehicles and turbine blades, to cite but three. Separation is difficult to predict with current turbulence models, and the design of devices that either lose their functionality or have their optimum performance close to the onset of separation is an engineering difficulty.

A vast amount of theoretical and/or experimental work has been presented throughout the past few decades, and lately direct numerical simulations (DNS) have become an important tool for further investigation of this type of flow. Although laboratory experimental techniques have improved and the reliability of results from experiments has increased, there is still need for DNS for improving the results in the near-wall region. Also, turbulent structures and the instantaneous flow fields can be more extensively analysed using DNS results.

1.1. Theoretical investigations

In most theoretical investigations of boundary layers it is of crucial importance to determine the relevant velocity scale. For a zero-pressure-gradient (ZPG) boundary layer such a velocity scale is naturally chosen as the friction velocity,

$$u_\tau \equiv \sqrt{v \left. \frac{\partial u}{\partial y} \right|_{y=0}}. \quad (1.1)$$

However, in the case of a boundary layer under an adverse pressure gradient (APG), u_τ is not the relevant velocity scale. This is true especially for strong APGs and low Reynolds numbers. For a separating boundary layer this is clear since u_τ becomes zero in this case. In a number of studies the case of a strong APG and separation has been investigated theoretically. In many such studies a velocity scale based on the

pressure gradient is defined,

$$u_p \equiv \left(\nu \frac{1}{\rho} \frac{dP}{dx} \right)^{1/3}. \quad (1.2)$$

In an analysis based on u_p , Stratford (1959) obtained a square-root law for the velocity profile from the assumption of zero wall stress and mixing length theory. Townsend (1961) refined the theory based on mixing length to the case of non-zero (but positive) wall shear stress and obtained a law with both square-root and logarithmic parts based on u_τ as a velocity scale. Kader & Yaglom (1978) extended the Stratford velocity profile to the case of positive wall stress. However, they kept the square-root law based on u_p , and accounted for the influence of a non-zero wall shear stress by varying the constants. Mellor (1966) arrived at a similar expression as Townsend. The work of Townsend was later reviewed by McDonald (1969) who included nonlinear inertia effects in the expression for the velocity profile.

Afzal (1996) obtained similar expressions for the velocity profile as Townsend by using asymptotic matching. Durbin & Belcher (1992) also used asymptotic theory for the analysis of velocity profiles. They obtained a three-layer structure of the turbulent boundary layer under an APG. Melnik (1989) also obtained a three-layer structure by extending the asymptotic analysis of Yajnik (1970) and Mellor (1972) with an algebraic turbulence model. Skote & Henningson (1999) simplified the formulation of Townsend and showed that the analysis could be valuable for turbulence modelling purposes.

Instead of using u_τ or u_p as the velocity scale and letting the velocity profile depend on the pressure gradient and Reynolds number, some investigators have tried to make the profiles collapse onto a single curve in an outer scaling. This seems to be possible only if a velocity scale is determined *a posteriori*, with the objective of making the profiles collapse. Coles (1956) proposed a wake function to account for the variation of the velocity profile in the outer (or wake) region of the boundary layer. The form of the wake function was later modified in a number of ways, see e.g. Musker (1979) for further references. Perry & Schofield (1973) and Schofield (1981) used a scaling for the outer part of the velocity profile designed to match the profiles to a half-power law close to the wall. They claimed that the velocity scale is related to the maximum shear stress.

Thus, there are two fundamentally different theoretical approaches to the velocity profile in a turbulent boundary layer under a strong APG. One is focusing on the local pressure gradient as the important parameter determining the shape of the velocity profile, the other is focusing on a velocity scale, defined through a fitting procedure, that will make the velocity profiles collapse onto a single curve. In this work we will develop further the analysis where the local pressure gradient is the key factor.

The dynamics of a separation bubble can depend on many parameters, such as the state of the upstream boundary layer and the strength of the APG. Thus, it is important to carefully consider the conditions under which the scaling laws are applicable.

1.2. Experiments

Many experiments have been performed on separated flows, although most of them consider separation caused by a sharp edge, or an obstacle. See, for example, the review of Simpson (1996) for a collection of references, and the work of Hancock (2000) for references to the latest experiments.

The experiments on separation of a flat-plate turbulent boundary layer include the

works of Perry & Fairlie (1975), Simpson, Strickland & Barr (1977), Simpson, Chew & Shivaprasad (1981*a,b*), Dengel & Fernholz (1990), Driver (1991) and Alving & Fernholz (1995, 1996). Some of these investigators have also tried to develop different scalings of the velocity profile in both outer and inner variables.

Simpson *et al.* (1977) showed that the Perry–Schofield scaling is supported upstream of separation, but with the streamwise derivative of the longitudinal and normal Reynolds stresses included in the estimation of the maximum shear stress. They concluded that the shear stress gradient is less than the streamwise pressure gradient due to the Reynolds stresses and the convective terms in the momentum equation.

Simpson *et al.* (1981*a,b*) developed a scaling based on the maximum back-flow velocity and its distance from the wall for the back-flow profile, which was shown to consist of three layers: the layer closest to the wall which is governed by viscous forces, a relatively flat intermediate layer and the outer back-flow which is dominated by the large-scale outer region flow. No universal ‘back-flow function’ could be found. Sufficiently far upstream of separation the logarithmic law was valid, as well as the Perry–Schofield scaling for the outer part. As separation is approached the scalings are not satisfied. Furthermore, they concluded that the velocity profile in the outer part is not described by a universal wake function. The normal and streamwise Reynolds stresses contribute to the turbulence energy production at separation, and the enhanced turbulence energy production in the outer region supplies turbulence energy to the back-flow region by turbulent diffusion.

Dengel & Fernholz (1990) performed measurements in an axisymmetric turbulent boundary layer. Three cases were investigated with skin friction zero, slightly negative and slightly positive. They concluded that the logarithmic law is not valid when the first reverse-flow events occur. Furthermore, the velocity profile does not confirm the Perry–Schofield scaling. Instead they represented an asymptotic velocity profile close to separation by a seventh-order polynomial. However, Dengel & Fernholz did not base the velocity scale on the maximum stress. Instead, they obtained the velocity scale by fitting the velocity profiles to a half-power law, as suggested by Schofield (1981). Reynolds stresses increased downstream in all three cases and the turbulence production maximum was far out in the boundary layer.

Driver (1991) performed measurements on two boundary layers on an axisymmetric body with similar pressure distributions but very different flows. One is attached and the other is separated. He concluded that above a certain value of the pressure gradient (in viscous scaling) the mean flow profile does not obey the law of the wall. The attached boundary layer was found to be in equilibrium and the Clauser parameter was nearly constant.

Alving & Fernholz (1996) performed an experiment on an axisymmetric body with a turbulent boundary layer that separates in a short region. They reported decreased Reynolds stresses in the inner region and large peaks away from the wall. After reattachment, the inner region is slower in its recovery than the outer part and the recovery does not start at the wall. Hence, the large-scale structures are intact over the separation bubble and then interact with near-wall flow after reattachment. Alving & Fernholz (1995) investigated the scaling of the velocity profiles from their experiment. They compared the Durbin–Belcher and Perry–Schofield scalings, with the conclusion that the latter performs better than the former. However, they did not use the velocity scale proposed by Perry & Schofield (1973), but rather determined their velocity scale so that the velocity profiles close to separation collapse with the profile given by Dengel & Fernholz (1990).

The consensus from the experiments mentioned above is that the turbulence is

intensified above a separated region while it is decreased in the back-flow region, compared to turbulence without separation. Velocity profiles at streamwise positions close to the separation point can only be made to collapse in the outer part by a fitting procedure of the velocity scale. Upstream of separation the experiments give no evidence on how the velocity profiles should be scaled. No universal profile for the back-flow seems to exist and the proper scaling is still an open question.

1.3. Direct numerical simulations

A few direct numerical simulations (DNS) of separated turbulent boundary layer flows have been performed earlier.

Na & Moin (1998*a,b*, hereafter abbreviated as NM), used a second-order finite difference method to simulate a turbulent separation bubble. The computational box was $350 \times 64 \times 50$ based on the displacement thickness δ^* at the turbulent inflow. The number of points was $513 \times 193 \times 129$. The inflow condition was taken from Spalart's (1988) temporal ZPG simulation. The velocity profiles were neither linear in the viscous sub-layer nor logarithmic further from the wall at all streamwise positions. The location of maximum turbulence intensity occurred above the separation bubble.

The near-wall flow from the simulation by NM has previously been investigated by Skote & Henningson (1999). Good agreement between theory regarding the viscous sub-layer (recapitulated here in §2.1.1) and DNS data was found in the region just upstream of separation.

Spalart & Coleman (1997, hereafter abbreviated as SC), performed DNS of a separation bubble with heat transfer. They used a spectral code with $640 \times 200 \times 256$ modes. Their inflow-outflow boundary condition was based on the fringe region technique with a turbulent inflow. Their results showed that separation has a large effect on the boundary layer, and that many assumptions which are valid for an attached layer cannot be applied to the separated boundary layer. The Reynolds shear stress increased dramatically over the separation bubble as did the turbulent kinetic energy. This is explained by a lift-up of turbulent fluid from the wall region that weakens the blocking effect of the wall. The increased turbulent energy can also be explained by a contribution from the normal and streamwise Reynolds stresses as argued by SC. Negative production of turbulent kinetic energy was observed in the later part of the separation bubble. This was not further explained by SC but was probably due to a positive Reynolds shear stress in that part of the flow. However, SC recognized that the effect of the rapid distortion on the boundary layer might lead to results which are not valid for turbulent separation bubbles in general.

In both of these simulations the boundary condition on the upper boundary was set by imposing a normal velocity that varies downstream and thus controls the separation bubble. Many results are hence similar for both simulations. The streamwise velocity profiles have a gradient at the upper boundary due to the boundary condition, thus the velocity profiles constitute a boundary layer with no free-stream edge, i.e. a location above which the normal gradient of the streamwise velocity and the normal velocity are small.

Both NM and SC noted that the streaks near the wall are eliminated by an APG. In NM they concluded that the vortical structures are lifted above the bubble and impinge on the wall in the reattachment region.

The simulations performed here are different from the ones by NM and SC in some important aspects. First, the separated region is longer than in NM and SC, hence the local distortion of the boundary layer is less severe. Second, the strength of the back-flow is stronger, which reveals new phenomena.

In this work we start with a review and extension of the theory concerning velocity profiles in an attached and separated turbulent boundary layer in § 2. The results from the simulations are presented in § 3. A presentation of the numerical methodology, including a resolution check, is given in § 3.1. This is followed by a general description of the flow in § 3.2, including both the instantaneous flow and turbulence statistics. The theoretical results from § 2 are compared with DNS data in § 3.3. The results are further discussed in § 4, and comparison with NM and SC will be made, as well as with some experimental data.

In the present work we focus on the near-wall flow since few results from the near-wall region in a separated flow have previously been reported. The flow close to the wall is scrutinized by comparing results from theoretical considerations with data obtained from the DNS.

2. The turbulent boundary layer equations

In the past, much effort has been put into obtaining numerically solvable ordinary differential equations for the parameters quantifying the turbulent boundary layer. See e.g. Schlichting (1979), Rotta (1962) and Cebeci & Smith (1974) for references. Using such methods, separation and reattachment can be predicted in some cases. However, no general formula to predict separation has been offered. The emphasis today is shifted towards more general closures of the Navier–Stokes equations, based on turbulence models. Therefore, no attempts to analyse or improve the methods based on simplified versions of the turbulent boundary layer equation (TBLE) are conducted here. The TBLE is used to extend and improve the theoretical understanding of the streamwise velocity profile in the inner region of the turbulent boundary layer.

The near-wall behaviour of a turbulent boundary layer close to separation, or fully separated, is difficult to analyse with the TBLE, since a separated flow does not permit the simplifications of the Navier–Stokes equations leading to the TBLE. However, even if the TBLE is not valid when the downstream development of a separating boundary layer is to be calculated, it can still be used to understand what happens locally in the boundary layer.

Results from a straightforward analysis of the TBLE is of importance for the development and calibration of turbulence models. The near-wall laws derived for ZPG boundary layers have been used extensively for obtaining boundary conditions in calculations of boundary layer flow with turbulence models. Thus, better near-wall laws for turbulent boundary layers would improve the predictions made of APG flows using turbulence models. The near-wall laws presented here can be used for such purposes.

In § 2.1 the analysis of the TBLE will be presented for two reasons. First we wish to strengthen the arguments and results from some previous authors. The analysis reported here clarifies how and under what circumstances previous results are applicable. Second, the modified analysis can be repeated for the separated case. This analysis is presented in § 2.2. The theoretical results for the separated case are derived from the same arguments as for the attached case. It is only the changed boundary condition at the wall that make the resulting expressions for the velocity profile different from the ones describing an attached boundary layer.

2.1. The attached boundary layer

The analysis of the TBLE will be divided into three parts. The first part deals with the total shear stress in the inner region of the boundary layer, where the advective

terms in the TBLE are neglected. The overlap region is investigated in the second part. In the third part, we will briefly discuss the outer part of the boundary layer.

2.1.1. The inner region

When neglecting the nonlinear advective terms in the equations describing the mean flow, the equation governing the inner part of the boundary layer is obtained. Using the inner length and velocity scales v/u_τ and u_τ , the following equation can be written:

$$0 = -\frac{v}{u_\tau^3} \frac{1}{\rho} \frac{dP}{dx} + \frac{d^2 u^+}{dy^{+2}} - \frac{d}{dy^+} \langle u'v' \rangle^+, \quad (2.1)$$

where $\langle u'v' \rangle$ is the Reynolds shear stress. If the term involving the pressure gradient is negligibly small compared to the other terms, the equation reduces to the equation governing the inner part of a ZPG boundary layer. However, for strong APG cases at finite Reynolds numbers, this term cannot be neglected. Equation (2.1) can be integrated to give an expression for the total shear stress,

$$\tau^+ \equiv \frac{du^+}{dy^+} - \langle u'v' \rangle^+ = 1 + \frac{v}{u_\tau^3} \frac{1}{\rho} \frac{dP}{dx} y^+. \quad (2.2)$$

For a ZPG case, equation (2.2) predicts a constant shear stress of unity in the inner region.

The pressure gradient term in equation (2.2) is evidently important for the shear stress distribution in the inner part of the boundary layer. This was observed in, among others, the experiments by Bradshaw (1967), Samuel & Joubert (1974) and Skåre & Krogstad (1994), and the DNS by Spalart & Watmuff (1993) and Skote, Henkes & Henningson (1998). It can be shown that the pressure gradient term decreases with increasing Reynolds number, and thus is important only for low Reynolds numbers. However, close to separation, where u_τ approaches zero, it is clear that the pressure gradient term becomes infinite, even for large Reynolds numbers.

When considering a strong APG or separation, the singularity mentioned above can be avoided by introducing the velocity scale u_p , defined in equation (1.2). To see this, we first formulate equation (2.2) as

$$\tau^+ = 1 + \left(\frac{u_p}{u_\tau} \right)^3 y^+. \quad (2.3)$$

The velocity scale u_p should be used instead of u_τ if the last term in equation (2.3) becomes very large, which happens if $u_\tau \ll u_p$, i.e. the boundary layer is close to separation. This was noted by Stratford (1959), Townsend (1961) and Tennekes & Lumley (1972). By multiplying equation (2.3) by $(u_\tau/u_p)^2$, the following expression for $\tau^p \equiv \tau/(\rho u_p^2)$ as a function of $y^p \equiv y u_p/v$ is obtained:

$$\tau^p = y^p + \left(\frac{u_\tau}{u_p} \right)^2. \quad (2.4)$$

Equation (2.4) has the asymptotic form $\tau^p = y^p$ when separation is approached. Thus, in this rescaled form, the singularity is avoided.

There are three possible complications in the above analysis. First, the pressure gradient (dP/dx) may depend on the normal coordinate (y). This proved to be important when the analysis was compared with the data from the simulation of NM, see Skote & Henningson (1999). However, due to the boundary conditions used in the present simulation, the pressure gradient is constant throughout the boundary

layer. The second complication is that the TBLE contains the streamwise derivative of longitudinal and normal Reynolds stresses. These terms may be important in a strong APG flow as was noted by Rotta (1962). A third complication is the nonlinear inertia terms, which can influence the total shear stress as argued by McDonald (1969). However, in the present simulations these two terms are not important and will be disregarded in the following.

Now, in the viscous sub-layer the Reynolds shear stress approaches zero and equation (2.4) can be integrated to give

$$u^p \equiv \frac{u}{u_p} = \frac{1}{2}(y^p)^2 + \left(\frac{u_\tau}{u_p}\right)^2 y^p. \quad (2.5)$$

In the limit of separation, when $u_\tau/u_p \rightarrow 0$, equation (2.5) reduces to

$$u^p = \frac{1}{2}(y^p)^2. \quad (2.6)$$

In viscous units, equation (2.5) becomes

$$u^+ = y^+ + \frac{1}{2} \left(\frac{u_p}{u_\tau}\right)^3 (y^+)^2. \quad (2.7)$$

This equation reduces to the usual linear profile in the ZPG case, when $u_p/u_\tau \rightarrow 0$.

The two expressions (2.5) and (2.7) depend on the Reynolds number and the pressure gradient and are equivalent. It is in the limits of $u_\tau/u_p \rightarrow 0$ and $u_p/u_\tau \rightarrow 0$ respectively that self-similarity is obtained and the choice of velocity scale becomes crucial.

2.1.2. The overlap region

We now proceed with the analysis by first considering the total shear stress. For the ZPG case, the scaling of the total shear stress with u_τ gives a self-similar profile ($\tau^+ = 1$). From equations (2.3) and (2.4) it is observed that neither u_τ nor u_p as velocity scale results in a self-similar expression. However, equation (2.2) can be formulated as

$$\tau^* \equiv \frac{1}{u_*^2} \left(\nu \frac{\partial u}{\partial y} - \langle u'v' \rangle \right) = 1, \quad (2.8)$$

where u_* is a velocity scale that depends on y and can be expressed in either viscous or pressure gradient units,

$$u_*^2 = u_\tau^2 + \frac{u_p^3}{u_\tau} y^+ = u_\tau^2 + u_p^2 y^p. \quad (2.9)$$

Thus, by scaling the total shear stress with u_* , a self-similar expression is obtained ($\tau^* = 1$). The velocity scale u_* reduces to u_τ if u_p becomes zero, i.e. for a ZPG boundary layer. If instead u_τ becomes zero, i.e. for a boundary layer at separation, the velocity scale becomes $u_* = u_p \sqrt{y^p}$. However, when $u_* = u_p \sqrt{y^p}$ is inserted in equation (2.8) we can write the equation as $\tau^p = y^p$, i.e. we use u_p as the velocity scale. Note that for the special case with $u_\tau = 0$, the velocity scale u_* is zero at the wall. This is consistent since the velocity gradient is zero at the wall.

The logarithmic behaviour of the turbulent boundary layer is obtained from the matching of the velocity gradient, or equivalently the shear stress, in the inner and outer regions of the boundary layer.

For the matching of the inner and outer equations, it is enough to observe that the

total shear stress can be written in the form (2.8) in the inner part. In the outer part it is assumed that the velocity gradient can be written

$$\frac{\partial u}{\partial y} = F' u_* / \Delta, \quad (2.10)$$

where F' is a function of a similarity variable ($\eta \equiv y/\Delta$) and Δ is the outer length scale. Equation (2.10) should be considered as the scaled formulation of the velocity gradient for the outer part, corresponding to the scaled velocity gradient for the inner part, which can be written as

$$\frac{\partial u}{\partial y} = f' u_*^2 / \nu, \quad (2.11)$$

where f' is a function of a similarity variable ($y^* \equiv y u_* / \nu$).

If the total shear stress is scaled with u_* in the outer and inner parts, and assumptions (2.10) and (2.11) are valid, then the matching of the total shear stress gives the equation

$$f' y^* = F' \eta. \quad (2.12)$$

Noting that the two sides of the equation depend on different variables, we set the first part equal to a constant and formulate it as

$$y^* \left(\frac{\partial u}{\partial y} \right)^* = \frac{1}{\kappa}, \quad (2.13)$$

where a short-hand notation is used for the scaled velocity derivative,

$$\left(\frac{\partial u}{\partial y} \right)^* \equiv \nu \frac{\partial u}{\partial y} \frac{1}{u_*^2}. \quad (2.14)$$

The scaled normal coordinate can be written

$$y^* = \sqrt{(y^+)^2 + (y^p)^3}. \quad (2.15)$$

For the ZPG case, for which $u_p = 0$, equation (2.13) is reduced to

$$y^+ \frac{du^+}{dy^+} = \frac{1}{\kappa}. \quad (2.16)$$

When integrated, equation (2.16) gives the logarithmic velocity profile.

In the same way as equation (2.16) can be integrated to give the logarithmic law for the ZPG case, equation (2.13) can be integrated to give a velocity profile in either viscous scaling ($u^+ \equiv u/u_\tau = f(y^+)$) or pressure gradient scaling ($u^p \equiv u/u_p = g(y^p)$). Both of these expressions will depend on the ratio between u_τ and u_p , and are thus not self-similar. A self-similar profile of the form $u^* \equiv u/u_* = h(y^*)$ is not consistent with equation (2.8). This is further discussed at the end of this section.

If u_τ is chosen as velocity scale, the integration of equation (2.13) yields

$$u^+ = \frac{1}{\kappa} \left(\ln y^+ - 2 \ln \frac{\sqrt{1 + \lambda y^+} + 1}{2} + 2(\sqrt{1 + \lambda y^+} - 1) \right) + B, \quad (2.17)$$

with

$$\lambda = \left(\frac{u_p}{u_\tau} \right)^3.$$

Expression (2.17) is not self-similar due to the term λ which is Reynolds-number

dependent. Equation (2.17) is the same expression as obtained by Afzal (1996). It is also similar to the equation which Townsend (1961) derived from mixing length arguments.

If u_p is chosen as velocity scale, then (2.17) can be written

$$u^p = \frac{1}{\kappa} \left(2\sqrt{\gamma^2 + y^p} + \gamma \ln y^p - 2\gamma \ln(\sqrt{\gamma^2 + y^p} + \gamma) \right) + C \quad (2.18)$$

where

$$\gamma = \frac{u_\tau}{u_p}.$$

For a ZPG boundary layer, for which $\lambda = 0$, equation (2.17) reduces to the logarithmic profile. In the other limit, at separation, when γ is zero, equation (2.18) reduces to the half-power law

$$u^p = \frac{1}{\kappa} 2\sqrt{y^p} + C, \quad (2.19)$$

which was first derived by Stratford (1959). Note that equation (2.19) can be rewritten such that it is independent of the viscosity, as in the formulation by Stratford.

As mentioned earlier, it is not possible to solve equation (2.13) directly to obtain an expression for u^* as a function of only y^* . This is due to the scaled (with u_*) velocity gradient, which cannot be formulated independently of u_τ and u_p . The velocity gradient scaled with a constant velocity scale u_τ or u_p is, on the other hand, straightforward to express independently of the Reynolds number:

$$v \frac{\partial u}{\partial y} \frac{1}{u_\tau^2} = \left(\frac{\partial u}{\partial y} \right)^+ = \frac{du^+}{dy^+}. \quad (2.20)$$

Thus, in the ZPG case the equation permits a self-similar velocity profile (the logarithmic function). The same is true for the zero wall stress case (the half-power law). In all flows between these two asymptotic states, the velocity profile depends on the Reynolds number and the pressure gradient.

2.1.3. The outer part

There have been many attempts to properly describe the velocity profile in the outer part of the boundary layer, both for ZPG and APG flows. Coles (1956) proposed a wake function for the description of the velocity profile. Since then a number of changes and refinements have been presented. Musker (1979), among others, proposed a velocity profile that is valid from the wall to the free stream, consisting of a logarithmic function and a wake function of the polynomial form. Dengel & Fernholz (1990) disregarded the form of the original wake function, and proposed a polynomial fit to the velocity profile. A different approach was chosen by Perry & Schofield (1973), who found their velocity scale by a fitting procedure similar to the Clauser plot in the ZPG case. They also related the velocity scale to the maximum shear stress, but no experimental data have confirmed this relation. Durbin & Belcher (1992) derived a three-layered structure of the turbulent boundary layer under a strong adverse pressure gradient. No experimental data have verified their scalings.

With this abundance of theories and proposed functions for the description of the velocity profile in the outer part, it is difficult to extract the ‘best’ theory, especially with those containing a large number of constants to be adjusted to obtain the best fit with DNS data.

The difficulties in finding an appropriate description of the velocity profile in the outer part of the boundary layer in strong APG flows with or without separation may be attributed to ‘historical effects’, i.e. the flow is not determined by local parameters (except for equilibrium layers), but is influenced by downstream and upstream conditions. This is consistent with the arguments of Perry (1966), who divided the boundary layer into a wall region, where the flow is determined by local parameters, and a ‘historical region’ where this local or ‘regional similarity’ does not apply.

No investigation of the outer part is presented in this work. However, Skote (2001) includes a study of the outer part of the boundary layer.

2.2. The separated boundary layer

In this section the case of separation will be discussed. The limit of zero shear stress ($u_\tau/u_p \rightarrow 0$) was approached in the analysis above, and the asymptotic version of the expression for the velocity in the viscous sub-layer was equation (2.6), and in the overlap region it was equation (2.19). These two expressions were obtained by setting $u_\tau = 0$ in equation (2.5) and (2.18) respectively. Now, if a separated flow is considered, the definition of u_τ has to be reconsidered. In the separated region, $\partial u/\partial y$ is negative, and the definition of u_τ in equation (1.1) involves a square root of a negative number. The definition will be changed so that the square root of a positive number will be taken. Thus, the definition of the friction velocity needs to be changed to

$$u_\tau \equiv \sqrt{-v \frac{\partial u}{\partial y} \Big|_{y=0}}. \quad (2.21)$$

This change will affect the analysis outlined in the previous section. It is the boundary condition at the wall used when integrating the TBLE that will be different from the attached case.

The equation for the inner part (2.1) will not be changed since the scaling is not affected by the change of definition of u_τ . However, in the integration leading to equation (2.2), the boundary condition at the wall is used and will now, with the definition (2.21), change sign. Thus, the analysis is the same as in §2.1. It is only the boundary condition that changes equation (2.4) to

$$\tau^p = y^p - \left(\frac{u_\tau}{u_p} \right)^2. \quad (2.22)$$

For the velocity in the viscous sub-layer the expression becomes

$$u^p = \frac{1}{2}(y^p)^2 - \left(\frac{u_\tau}{u_p} \right)^2 y^p, \quad (2.23)$$

instead of equation (2.5). Due to the changed boundary condition, the corresponding equation in viscous scaling, equation (2.7), is

$$u^+ = -y^+ + \frac{1}{2} \left(\frac{u_p}{u_\tau} \right)^3 (y^+)^2. \quad (2.24)$$

Note that the equations (2.5) (attached boundary layer) and (2.23) (separated boundary layer) take the same form,

$$u^p = \frac{1}{2}(y^p)^2, \quad (2.25)$$

when $u_\tau/u_p \rightarrow 0$. This asymptotic form is equal for the two cases since the asymptotic

state is the onset of separation. On the other hand, the corresponding equations in the viscous scaling, equations (2.7) and (2.24), have the asymptotic forms $u^+ = y^+$ and $u^+ = -y^+$ respectively. Thus, the assumption that viscous forces are stronger than the pressure gradient gives different profiles in the attached and separated region.

From equation (2.5) or (2.24) it is possible to extract the maximum negative velocity and the position where it occurs. In pressure gradient scaling the maximum back-flow is $-\frac{1}{2}(u_\tau/u_p)^4$ at $y^p = (u_\tau/u_p)^2$. These results are valid if the back-flow maximum is located in the viscous sub-layer.

Now the logarithmic part of the boundary layer will be discussed. According to equation (2.22), the velocity scale that produce a self-similar shear stress ($\tau^* = 1$) is

$$u_*^2 = -u_\tau^2 + \frac{u_p^3}{u_\tau} y^+ = -u_\tau^2 + u_p^2 y^p. \quad (2.26)$$

By inserting either form of u_* into equation (2.13), two different expressions for the velocity profile are obtained. Using the viscous scaling yields

$$u^+ = \frac{1}{\kappa} [2\sqrt{\lambda y^+ - 1} - 2 \arctan(\sqrt{\lambda y^+ - 1})] + B, \quad (2.27)$$

with

$$\lambda = \left(\frac{u_p}{u_\tau} \right)^3.$$

By using the pressure gradient scaling we obtain

$$u^p = \frac{1}{\kappa} \left[2\sqrt{y^p - \gamma^2} - 2\gamma \arctan \left(\sqrt{\frac{y^p}{\gamma^2} - 1} \right) \right] + C, \quad (2.28)$$

where

$$\gamma = \frac{u_\tau}{u_p}.$$

The logarithmic dependence has been replaced by the arctan function. However, the asymptotic function (2.19) is recovered from equation (2.28) when $u_\tau/u_p \rightarrow 0$.

Equation (2.27) was actually derived by McDonald (1969) from Townsend's extended log law, but with the velocity scale u_p replaced by the shear stress gradient. McDonald argues that the shear stress gradient is different from the streamwise pressure gradient, and that the deviation originates from inertia effects.

3. Direct numerical simulations

3.1. Numerical considerations

3.1.1. Numerical method and parallelization

The code used for the direct numerical simulations (DNS) was developed at KTH and FFA (Lundbladh *et al.* 1999). The numerical approximation consists of spectral methods with Fourier discretization in the horizontal directions and Chebyshev discretization in the normal direction. Since the boundary layer is developing in the downstream direction, it is necessary to use non-periodic boundary conditions in the streamwise direction. This is possible while retaining the Fourier discretization if a fringe region is added downstream of the physical domain. In the fringe region the flow is forced from the outflow of the physical domain to the inflow. In this way the physical domain and the fringe region together satisfy periodic boundary

FIGURE 1. SEP: Contours of mean velocity. Positive values shown as solid lines, negative as dashed. Note that the vertical scale is twice the horizontal.

conditions. The fringe region is implemented by the addition of a volume force F to the Navier–Stokes equations:

$$\frac{\partial u_i}{\partial t} + u_j \frac{\partial u_i}{\partial x_j} = -\frac{1}{\rho} \frac{\partial p}{\partial x_i} + \nu \frac{\partial^2 u_i}{\partial x_j^2} + F_i. \quad (3.1)$$

The force

$$F_i = \lambda(x)(\tilde{u}_i - u_i) \quad (3.2)$$

is non-zero only in the fringe region; $\tilde{u}_i$ is the laminar inflow velocity profile to which the solution u_i is forced and $\lambda(x)$ is the strength of the forcing. The form of $\lambda(x)$ is designed to minimize the upstream influence. For an analysis of the fringe region technique, the reader is referred to Nordström, Nordin & Henningson (1999). The whole computational box is shown in figure 1 to illustrate the fringe region technique. The flow is laminar at $x = 0$ and the transition takes place up to approximately $x = 65$ (cf. figure 4). The reverse flow in the separation bubble is indicated with the dashed contours. From $x = 550$ to $x = 700$ is the fringe region where the turbulence is damped and the laminar profile at $x = 0$ is restored.

Time integration is performed using a third-order Runge–Kutta method for the advective and forcing terms and a Crank–Nicolson method for the viscous terms. A 2/3-dealiasing rule is used in the streamwise and spanwise directions.

The simulations were performed to a large extent on computers with distributed memory. The parallelization and optimization of the code for this type of computer were performed by Alvelius & Skote (2000).

The boundary conditions are no-slip at the wall and at the free stream ($y = 65$) the normal derivative of the streamwise and spanwise velocity components are set to zero, while for the normal component the prescribed value of the APG is used,

$$\frac{\partial v}{\partial y} = \frac{\partial V_{APG}}{\partial y} = -\frac{\partial U_{APG}}{\partial x}. \quad (3.3)$$

These boundary conditions ensure that the prescribed APG is obtained.

3.1.2. Numerical parameters

The simulations were performed on various computers. The tuning of the pressure gradient for the desired flow situation was performed on a Cray T3E at NSC in Linköping, using 32 processors. After the design of the pressure gradient, a simulation with 20 million modes was performed on an IBM SP2 at PDC, KTH in Stockholm, using 32 processors. The results presented here are mainly from a second simulation with 40 million modes performed at the National Aerospace Laboratory (NAL), Tokyo. The computer used at NAL was the Numerical Wind Tunnel (NWT), a parallel computer that consists of 166 vector processors from Fujitsu.

The simulations start with a laminar boundary layer at the inflow which is triggered

FIGURE 2. SEP: Velocity profile in the separated region at $x = 350$ and in the attached region at $x = 500$. —, $720 \times 217 \times 256$ modes; ---, $512 \times 193 \times 192$ modes.

to transition by a random volume force near the wall. All the quantities are non-dimensionalized by the free-stream velocity (U) and the displacement thickness (δ^*) at the starting position of the simulation ($x = 0$), where the flow is laminar. At that position $Re_{\delta^*} = U\delta^*/\nu = 400$. The length (including the fringe), height and width of the computation box were $700 \times 65 \times 80$ in these units. The fringe region has a length of 100 and the trip is located at $x = 10$.

Results from two simulations are presented. One, which is called APG1, is a boundary layer subject to a strong APG. The flow in APG1 is everywhere attached. The second, which is called SEP, is a boundary layer under an even stronger APG, and a large portion of the flow is separated.

Two different resolutions were used for the simulations. For APG1 the number of modes was $512 \times 193 \times 192$. After a simulation of SEP with the same resolution, a larger simulation was performed using the NWT. The number of modes in this simulation was $720 \times 217 \times 256$, which gives a total of 40 million modes or 90 million collocation points.

The lateral domain size was chosen based on earlier DNSs of APG boundary layers. The simulations were run for a total of 7500 time units (δ^*/U), and the sampling for the turbulent statistics was performed during the last 2500 time units. The statistics were collected during the simulations and averaged in the spanwise direction. No filtering of the statistics has been used.

3.1.3. Resolution check

The simulation of a separated boundary layer was performed with two different resolutions which could be compared with each other. The turbulent statistics for both resolutions were computed from the same amount of simulation time. The general behaviour in the streamwise direction is the same for the two resolution, i.e. there are no large differences in parameters such as friction velocity, shape factor etc. There were some differences in the region where the back-flow has its largest magnitude, which is now further investigated. Velocity profiles from two downstream positions are shown in figure 2, one at $x = 350$ where the back-flow is strongest, and one at $x = 500$, where the boundary layer is attached. A large part of the profile from the less resolved simulation at the point of maximum back-flow ($x = 350$) is below the profile from the well-resolved simulation. However, close to the wall they collapse. In the attached region, the two profiles are essentially similar. Thus, the region where strong back-flow occurs is sensitive to the resolution, which means that caution is needed when simulating this type of flow. Also, in the Reynolds shear stress some

	Present	NM	SC
Δx	0.65	0.85	0.57
Δy	0.30	0.41	0.27
Δz	0.21	0.48	0.21

TABLE 1. Comparison of resolution between the present simulation and the simulations by SC and NM.

FIGURE 3. SEP: Energy contained in modes in —, x ; ---, y ; ···, z . Thick lines: $720 \times 217 \times 256$; Thin lines: $512 \times 193 \times 192$.

differences could be detected, most notably in the outer region, near the free stream. In the attached region there were no differences between the two resolutions for the Reynolds stresses. It should be noted that even though the history effects can influence the boundary layer downstream of reattachment (see e.g. the investigations of Alving & Fernholz 1996), the differences upstream of reattachment in the two resolutions do not influence the boundary layer in the attached region.

This investigation shows that the lower resolution is sufficient for the attached region, while in the separated region, the high resolution is crucial for capturing the correct behaviour.

Comparison with the resolution in the simulations by NM and SC is possible by rescaling the size of the box of their simulations in the coordinates of the present simulation and dividing with number of collocation points. The result is shown in table 1. The resolution is better for the present simulation than in NM in all three directions, even though their method has second-order accuracy while our method, as in SC, is spectral.

To further confirm the resolution we show the energy in the flow as function of the spectral modes for the two resolutions in figure 3. The thick lines are from the well-resolved case. Note that the two velocity fields are for different times, thus the curves from the two cases do not collapse. The energy decays consistently in the three directions when the resolution is refined. The small contamination in the highest modes moves to higher wavenumbers as resolution is increased.

Since the simulation starts with a laminar boundary layer, the transition to turbulence is an important part of the flow, even though we are only interested in the fully turbulent region of the flow. The evolution of the turbulence might be influenced if the transition is poorly resolved. The turbulence may also contain memory effects of the transition if the triggering of the laminar flow is not performed carefully.

FIGURE 4. APG1: —, U ; $\cdots$, $C_f \times 100$. SEP: ----, U ; - · -, $C_f \times 100$. S and R denotes point of separation and reattachment respectively for SEP.

FIGURE 5. V : —, APG1; ----, SEP.

3.2. General description of the flow

3.2.1. Mean flow parameters

In earlier simulations of APG turbulent boundary layers by the authors of the present work, Skote *et al.* (1998), the free-stream velocity varied according to a power law in the downstream coordinate, $U \sim x^m$. The motivation for this was that a self-similar profile in the outer part could be developed. In the simulations presented here, the aim was to obtain a boundary layer as close to a separated state as possible. The tuning of the pressure gradient is extremely time consuming since the boundary layer has a slow response to any change in the pressure distribution. The value of m was -0.23 in APG1 and -0.35 in SEP.

The free-stream velocity (U) for the two simulations, APG1 and SEP, is shown in figure 4, together with the skin friction (C_f). As seen from the figure, a small change in the free-stream velocity has a great impact on the skin friction. A number of simulations were performed to obtain a boundary layer with a wall shear stress as close to zero as possible. These two simulations are the ones where we obtained u_τ closest to zero, and were therefore continued for a long time to obtain good statistics.

Even if the boundary condition (U) is almost the same for the two simulations, the resulting boundary layers contain very different flows. In APG1 the boundary layer is subject to a strong APG, but is everywhere attached. In SEP the boundary layer is separated for a large portion of the computational domain. The resulting normal velocity at the free-stream boundary (V) is shown for the two cases in figure 5.

The ratio between the two velocity scales (u_τ/u_p) is shown in figure 6 for the two

FIGURE 6. u_τ/u_p : —, APG1; ---, SEP.

cases. The ratio is fairly constant for APG1, and for SEP the variation is not large except close to the separation and reattachment points. This is in strong contrast to the rapid separation and attachment simulated by SC and NM. The almost constant ratio will have some consequences for the scaling of the velocity profiles shown in §3.3.

The strong decrease in the skin friction before the reattachment cannot be explained by the mean momentum equation alone. The point of reattachment cannot be predicted either, but can be detected from the behaviour of the normal velocity at the free-stream boundary (figure 5). At the beginning of the computational domain the flow out of the box is generated by the strong decrease in the streamwise velocity. Later, the flow is inward, due to the fringe region, where the original, laminar boundary layer is restored. With a longer computational box, the point of reattachment would move downstream. The influence of the fringe is however not unphysical, since it only determines the boundary condition at the outflow. The boundary layer has to end somewhere, and this scenario is just one example.

3.2.2. Instantaneous flow

To illustrate some features of the instantaneous flow in the separated case, contour plots of constant streamwise and normal total velocities are plotted in a part of the computational box in figure 7. The streamwise velocity, plotted in dark grey, shows a less ordered structure than in a ZPG boundary layer. The sheet formed by the constant value is bent upward over the recirculation region and comes down again when approaching reattachment. This is in agreement with various experimental observations, see the introduction.

The normal velocity is shown in light grey and has a positive value. Thus, the fluid is flowing out of the computational box due to the APG. The normal velocity is of the same disorganized form as the streamwise velocity. Note that the figure does not show the entire computational box in the normal (y) and streamwise (x) directions.

The streamwise velocity fluctuations for APG1 and SEP are shown in figure 8 which shows the whole computational box in the spanwise direction but the transitional part and fringe region are excluded in the streamwise direction.

The streamwise velocity fluctuations form elongated structures (streaks) near the wall in a ZPG boundary layer, spaced 100 viscous units in the spanwise direction.

It is generally thought that the structures are weakened in an APG flow. This is illustrated in figure 8(a), where shades of positive and negative fluctuations are shown for the APG1 case. The normal position is $y^+ = 11.8$ at the beginning and $y^+ = 9.2$

FIGURE 7. The separated boundary layer. Only a part of the computational box is shown. The light grey structures represent positive normal velocity and the darker ones represent positive streamwise velocity.

at the end. The length in the streamwise direction is about 3400 viscous units based on u_τ at $x = 350$. The structures are weakened at the end of the domain compared with those in the beginning, showing the damping effect of the APG on the structures. The spacing between the structures increases from 100 (the same as for a ZPG layer) at the beginning to about 130 at the end, based on the local u_τ .

The SEP case is shown in figure 8(b). The normal position is also in this case around $y^+ = 10$ and the length of the region shown is about 2400 (based on u_τ at $x = 350$). There are still some structures in the separated flow, though not as long and frequent as in APG1. Before separation, which occurs at approximately $x = 140$, the streaks are visible, but are rapidly vanishing in the beginning of the separated region. There is a notable increase in the streak formation around $x = 350$, where the friction coefficient is at its lowest values, cf. figure 4. Thus, there are indications that streaks may reappear in a separated region if the back-flow is strong enough. After the reattachment at $x = 412$ the streaks do not immediately appear, but are clearly visible after $x = 450$.

3.2.3. Turbulence statistics

The turbulent kinetic energy and its production presented in this section are scaled with the inlet free-stream velocity and displacement thickness. For the APG1 case the development of the turbulent kinetic energy is typical for an APG turbulent boundary layer. In figure 9 contours of constant levels of turbulent kinetic energy from 0.0005 to 0.006 are shown. The peak value is around 0.006 at all streamwise positions. It is slightly larger at the beginning and decreases slowly downstream, while the position of the peak is shifted outward from $y = 4$ at $x = 150$ to $y = 18$ at $x = 550$.

The turbulent kinetic energy development in SEP is more complicated and will be discussed with the aid of figure 10, where contours of constant levels of turbulent kinetic energy from 0.005 to 0.025 are shown. At $x = 150$ the boundary layer has barely separated and the energy has one maximum of 0.0016 located far out in the boundary layer (approximately at $y = 18$). Further downstream, at position $x = 250$,

FIGURE 8. Streamwise velocity fluctuations in a horizontal plane at approximately $y^+ = 10$ (at $x = 350$). The dark area represents low-speed fluid. (a) APG1, (b) SEP. The points denoted S and R represent separation and reattachment respectively.

FIGURE 9. APG1: Contours of turbulent kinetic energy. Values from 0.0005 to 0.006.

FIGURE 10. SEP: Contours of turbulent kinetic energy. Values from 0.005 to 0.025.

FIGURE 11. SEP: Contours of shear production ($-\langle u'v' \rangle \partial u / \partial y$) of turbulent kinetic energy. Positive values shown as solid lines, negative as dashed. Values from -3.5 to 8.5 .

the energy maximum has shifted outward to $y = 30$ with the larger value 0.025. The profile then stays approximately the same until the maximum starts to decrease and is moving towards the wall after $x = 330$. When comparing with the mean streamwise velocity in figure 1, it is noted that the peak in turbulent kinetic energy is located outside the recirculation zone. This was also noted by SC and Alving & Fernholz (1996) among others (see the introduction). At $x = 350$ the profile of the energy is almost identical with the one at $x = 150$, but the maximum continues to decrease downstream, even though the location ($y = 18$) of the maximum is constant. The boundary layer is still subjected to an adverse pressure gradient, and the peak located far out in the boundary layer is a consequence of this. Nothing unusual occurs at the point of reattachment ($x = 412$). The peak value is stabilized after $x = 450$ at a value of 0.006, which is the same value as observed in the APG1 case. That the maximum value, and even the profile, of turbulent kinetic energy after reattachment resembles the corresponding profile in the APG1 case, points to the local pressure gradient being a very important factor. Thus, this observation strengthens the argument that the local parameters are of importance for describing the flow, at least close to the wall, and that the history of the boundary layer is less significant there.

The shear stress contribution to the production is shown in figure 11 for SEP. Approximately the same behaviour as for the energy itself is observed up to $x = 330$. The maximum occurs closer to the wall, but still above the recirculation region. Between $x = 350$ and $x = 400$ is a region of negative production (destruction) above the wall which originates from positive values of the Reynolds shear stress in that region. The maximum value of the Reynolds shear stress, at the same position as where the maximum destruction occurs, is 0.0036. This should be compared with the

FIGURE 12. SEP: Contours of normal production $((\langle v'v' \rangle - \langle u'u' \rangle) \partial u / \partial x)$ of turbulent kinetic energy. Positive values shown as solid lines, negative as dashed. Values from -3.5 to 8.5 .

minimum value of -0.0057 . It seems that even though the area of positive Reynolds shear stress is small, the magnitude is of the same order as the (usual) negative values.

The streamwise and normal Reynolds stresses contribute to the production as shown in figure 12, where this part of the production (by the term $(\langle v'v' \rangle - \langle u'u' \rangle) \partial u / \partial x$) is shown. We denote it the normal production, and it is fluctuating more rapidly over the boundary layer than the production originating from the shear stress. To obtain a clear picture the data has been low-pass filtered in x with a filter width of 5. The normal production has its maximum at increasing y -positions until $x = 300$ where the negative (destruction) values appear.

From figures 11 and 12 one can also conclude that the total production is negative in a region upstream of reattachment. This was also observed in the DNS of SC.

In the DNS of NM no negative total production in the middle of the layer occurred, even though the production of Reynolds shear stress showed negative values both close to the wall and in the middle of the boundary layer.

3.3. Comparison with analysis

To compare the DNS data with the results from §2, the mean flow profiles will be presented in different scalings and from different parts of the boundary layer. From figure 2 it is observed that the back-flow is very weak compared to the free-stream velocity. The portion of the boundary layer where back-flow exists is small compared to the portion with positive streamwise velocity. But, the flow close to the wall is important because it determines many of the features of the flow that are crucial from an engineering aspect.

From APG1 the data are compared with the results from the analysis of the TBLE for an attached boundary layer (§2.1). From SEP the data are compared with the results from the analysis of the TBLE for a separated boundary layer (§2.2).

3.3.1. Velocity scales

To give some idea what the different scalings of the normal coordinate presented in §2 mean, we show the three different scalings for one streamwise position in figure 13(a). The y^+ and y^p depend linearly on y since the velocity scales u_τ and u_p are independent of y . The difference in the slope of y^+ and y^p versus y is determined by the ratio of u_τ and u_p . Note that y^* approaches y^+ close to the wall.

The analysis of the overlap region in §2.1.2 depended on the velocity gradient being written as equation (2.11). In figure 13(b) the function $f' = (\partial u / \partial y)^*$ is shown for three different streamwise positions. The function has approximately the same shape, which is consistent with equation (2.11). There is however no perfect self-similarity, which is not surprising at the low Reynolds number we are considering here.

FIGURE 13. APG1: (a) Scaled normal coordinate at $x = 300$. —, y^* ; ---, y^p ; ···, y^+ .
(b) Velocity gradient at —, $x = 200$; ---, $x = 300$; ···, $x = 400$.

FIGURE 14. Velocity profiles at $x = 150$ to $x = 500$. (a) APG1: —, DNS; ---, $u^+ = y^+$.
(b) SEP: —, DNS; ---, $u^+ = y^+$; - · -, $u^+ = -y^+$.

3.3.2. The viscous sub-layer

The near wall profiles are plotted in the viscous scaling in figure 14 and are compared with the profiles given by the asymptotic versions of equations (2.7) and (2.24). For APG1 the collapse is good as seen in figure 14(a). For the case SEP, shown in figure 14(b), the profiles close to the $u^+ = y^+$ profile are the two in the attached region at positions $x = 450$ and $x = 500$. The profiles furthest from both asymptotes are taken from the positions closest to separation and reattachment, while the lowest (closest to $u^+ = -y^+$) is from the position with strongest back-flow.

In figure 15 the same profiles are shown in pressure gradient scaling and are compared with the profiles given by the asymptotic expression (2.25), which is the same for the attached and separated case. The profiles are spread equally in the viscous scaling and in the pressure gradient scaling due to the ratio u_τ/u_p being nearly constant, see figure 6. This is in strong contrast to the simulation of NM, where the variation in u_τ was enhanced by the rapidly growing pressure gradient. In their simulation, the velocity profiles collapsed much better when scaled with u_p than u_τ (see Skote & Henningson 1999). Figure 15 shows that the profiles are further from the asymptotic state (separation) than in the viscous scaling (figure 14), where the profiles showed some similarity with the asymptotic (ZPG) profile.

Velocity profiles in the pressure gradient scaling at two downstream positions are

FIGURE 15. Velocity profiles at $x = 150$ to $x = 500$. (a) APG1: —, DNS; ---, $u^p = \frac{1}{2}(y^p)^2$. (b) SEP: —, DNS; ---, $u^p = \frac{1}{2}(y^p)^2$.

FIGURE 16. Velocity profiles in pressure gradient scaling. (a) APG1: —, DNS; ---, $\frac{1}{2}(y^p)^2 + (u_\tau/u_p)^2 y^p$. (b) SEP: —, DNS; ---, $\frac{1}{2}(y^p)^2 - (u_\tau/u_p)^2 y^p$.

shown in figure 16, together with the theoretical expressions for the velocity profile in the viscous sub-layer. For APG1 (figure 16a) the positions are $x = 200$ and $x = 450$, and for SEP (figure 16b) they are $x = 200$ and $x = 300$. Here the asymptotic curve is not shown, but the pressure-gradient-dependent curves from equation (2.23) are shown. The DNS profiles and the corresponding curves given by equation (2.23) follow each other and show that even if the profiles are far from the asymptotic state (as shown in figure 15), the inclusion of the pressure gradient term gives a good agreement.

In summary, figure 14 shows that the scaling with u_τ works for APG1 but not for SEP. Figure 15 shows that the scaling with u_p does not work for APG1, nor for SEP, while figure 16 shows that with the inclusion of the pressure gradient term, the scaling with u_p works well in both cases.

3.3.3. The overlap region

The laws presented in §2.1.2 are compared with data from the simulations in figure 17, and the results from §2.2 regarding the overlap region are presented in figure 18.

For APG1 the extended logarithmic law (2.17) gives profiles that are more in agreement than the usual ZPG logarithmic law, see figure 17(a). However, the value

FIGURE 17. (a) APG1: Velocity profile at $x = 350$. —, DNS; ---, equation (2.17) with $\kappa = 0.41$ and $B = 1.5$ ($\lambda = 0.069$); $\cdots$, $u^+ = (1/0.41) \ln y^+ + 5.1$. (b) SEP: Velocity profile at $x = 450$. —, DNS; ---, equation (2.17) with $\kappa = 0.41$ and $B = -2$ ($\lambda = 0.076$); $\cdots$, $u^+ = (1/0.41) \ln y^+ + 5.1$.

FIGURE 18. (a) SEP: Velocity profiles at $x = 150$ and $x = 300$. —, DNS; ---, equation (2.27) with $\kappa = 0.41$ and $B = -7$; $\cdots$, $u^+ = (1/0.41) \ln y^+ + 5.1$. (b) SEP: Velocity profile at reattachment $x = 412$. —, DNS; ---, $u^p = (1/0.41)2\sqrt{y^p} - 7$ (equation (2.28) with $\gamma = 0$ and $C = -7$).

of the additive constant B in equation (2.17), which has a value of -2 close to separation in both DNS and experiments, had to be set to $+1.5$ to fit the DNS data in APG1. This is true for all streamwise positions, and hence the value of the additive constant seems to depend on the pressure gradient, and not the Reynolds number. In the attached region of the separating boundary layer, the profile from equation (2.17) with $B = -2$ gives the best approximation, shown in figure 17(b). This is in agreement with the earlier investigation of the flow just upstream of separation in the simulation of NM, see Skote & Henningson (1999).

The profiles in the separated region, figure 18(a), are compared with the arctan law derived in §2.2. The profile given by equation (2.27) is in much better agreement with DNS than the corresponding ZPG law, also shown in the figure. The additive constant is -7 for the separated case. It should also be noted that the extended logarithmic law derived for an attached layer under a strong APG, equation (2.17), gives a poor agreement with DNS data in the separated region (not shown in the figure). At the point of reattachment ($x = 412$) the profile is given in pressure gradient scaling in figure 18(b). The asymptotic version of equation (2.28) is in good agreement with DNS data since u_τ is close to zero.

Thus, the conclusion is that the equations describing the overlap region derived

FIGURE 19. V and U : —, SEP; ---, NM. The profile starting from unity is U .

in §2 are in qualitative agreement with DNS data, and are far more consistent with DNS data than the corresponding ZPG laws.

However, due to the low Reynolds numbers, it is not possible to draw any definite conclusions regarding the overlap region. To properly clarify these matters, high-Reynolds-number data are required, and the experiments of Alving & Fernholz (1996) are therefore analysed in §4.

4. Discussion

In this section a discussion of the relation between our results and others is presented.

4.1. Comparison with earlier DNS

The separated turbulent boundary layer simulated by DNS presented here has different characteristics than earlier DNS of a separation bubble. Efforts have earlier been made to create a bubble that starts and ends with a ZPG turbulent boundary layer. In the simulation presented here, the boundary layer is everywhere subject to an APG. To obtain a bubble with such a small extent in the streamwise direction, as in the simulations of NM and SC, requires a strongly varying pressure gradient in order to force the boundary layer to separate and then reattach. The pressure gradient in those simulations was imposed by a strongly varying normal velocity at the free-stream edge. This, in turn, creates a large normal gradient in the mean flow at the upper boundary. Here, the streamwise pressure gradient does not vary as rapidly as in the earlier DNS. However, the boundary layer reattaches upstream of the fringe region even if no favourable pressure gradient is applied. The variation of the normal velocity is much weaker than in NM, see figure 19. The free-stream V varies approximately in the same way in SC as in NM. Here their x and y values have been recalculated in our simulation coordinates. However, the relative starting positions of the boundary layers cannot be calculated because the NM and SC simulations started with a turbulent boundary layer while our simulation starts with a laminar one that undergoes transition. In the comparison here, we simply present the results from the starting point ($x = 0$) of each simulation.

The integrated quantities, such as the shape factor and momentum thickness, cannot be compared with data from earlier DNS of separated flow by SC and NM. This is due to the behaviour of the velocity profiles in the free stream in those simulations. At some streamwise position the maximum value of u is located in the middle of the boundary layer, and the value at the upper boundary is three times lower. Figure 20

FIGURE 20. Velocity profiles. —, SEP; ---, NM; ···, SC.

FIGURE 21. C_f : —, SEP; ---, NM; ···, SC.

shows velocity profiles at the position of maximum back-flow from the three different simulations. The profiles from NM and SC show a considerable velocity gradient at the upper boundary, and the value at the upper boundary of U varies strongly in NM, as seen from figure 19.

The strong gradient in the free stream in the NM and SC simulations makes it difficult to define a boundary layer edge. From figure 20 it is also clear that the back-flow is stronger in the present simulation than in NM and SC.

Since there was no real free stream in SC and NM, the friction coefficient, C_f , was calculated with the value of unity for the free-stream velocity U at all streamwise positions. Comparison of the C_f from NM and SC with our simulation is made in figure 21. It is clear from figure 21 that our separation bubble is longer than the other two. In figure 21 the C_f from our simulation has been calculated using the same technique as in NM and SC, i.e. with a value of unity for the free-stream velocity.

A possible criticism of our simulation technique is the inflow condition. The laminar boundary layer undergoes transition and becomes turbulent under the influence of the APG. This raises the question of whether the turbulence downstream is in equilibrium or is influenced by the transitional region. Our results point towards the turbulence having no memory of the transition and there being no dependence on the trip at the beginning of the flow. The argument is simply that the theoretical profiles (which have no memory of transition) coincide with the DNS results. This is also connected to another issue: the importance of local parameters. The profiles (close to the wall) are determined by local parameters and do not strongly depend on the history of the turbulence. This is also evident in the profiles after reattachment which still depend

FIGURE 22. Experimental data from Alving & Fernholz (1995). (a) Velocity profiles upstream of separation: ----, equation (2.17) with $\kappa = 0.41$ and $B = -2$. (b) Velocity profiles in the separated region: ----, equation (2.17) with $\kappa = 0.41$ and $B = -2$; ····, equation (2.27) with $\kappa = 0.41$ and $B = -7$.

only on local parameters even though the boundary layer has been seriously distorted by separation upstream.

We do not present any RANS calculation of the present cases. However, the data from both APG1 and SEP have been used for the development of new and successful turbulence models, see Skote & Wallin (2000) or Skote (2001).

4.2. The overlap region in experiments

To further investigate the theoretical expressions from § 2.1.2, but at a larger Reynolds number than is possible to reach with DNS, the experimental data from Alving & Fernholz (1995, 1996) are investigated.

In the work of Alving & Fernholz (1995) the velocity profiles showed considerable departure from the law of the wall valid for ZPG flow. By using the Perry–Schofield coordinates, modified by Dengel & Fernholz (1990), the curves were forced to collapse. However, the procedure of determining the velocity scale *a posteriori*, from the collapsed velocity profiles, make the analysis less valuable. The measured profiles are here examined from the other standpoint, the extended law of the wall. In figure 22 the profiles before separation and in the separated region are shown. Upstream of separation the extended logarithmic law (2.17) with the standard value of -2 for the additive constant predicts the profiles well. In the separated region (only one profile available) the profile given by equation (2.27) gives a better prediction than equation (2.17). However, a change in the additive constant in equation (2.17) can make the agreement with the experimental profile equally good.

Thus, the experimental data of Alving & Fernholz confirm and strengthen the conclusion drawn from our DNS data in § 3.3.3.

4.3. Comparison with other theories for the overlap region

A number of investigators have, with different methods, tried to obtain the theoretical velocity profile in APG flows, corresponding to the logarithmic profile in a ZPG flow.

According to Tennekes & Lumley (1972), the scaling with the pressure-gradient velocity u_p (with $u_\tau = 0$) should lead to the same form of matching as in the zero pressure gradient case. From this assumption a logarithmic law is obtained in the

FIGURE 23. SEP: Velocity profiles at $x = 200$, $x = 250$, $x = 300$, $x = 350$ and $x = 400$. u_N and N are the maximum mean back-flow velocity and its distance from the wall; ----, profile from equation (4.4).

same manner as the usual procedure of matching the outer and inner solutions. The log law becomes

$$u^p = \frac{1}{\kappa} \ln(y^p) + B. \quad (4.1)$$

Our analysis has shown that the change of velocity scale from u_τ to u_p does not permit the analysis leading to equation (4.1), but instead yields the half-power law, equation (2.19).

According to Stratford (1959), the velocity profile should be a half-power law close to separation. Also Yaglom (1979) showed that a dimensional analysis gives the following expression for the velocity profile close to separation:

$$u^+ = K^+ \sqrt{\lambda y^+} + K_1^+, \quad (4.2)$$

which can be expressed in pressure gradient scaling as

$$u^p = K \sqrt{y^p} + K_1. \quad (4.3)$$

Yaglom (1979) also proposed a fairly complicated dependence of K and K_1 on u_p and u_τ . This dependence was introduced to extend the theory valid at separation to the region upstream of detachment. It may not be regarded as a sound procedure, however, to incorporate a functional behaviour in constants of an expression valid only in an asymptotic state.

4.4. Alternative scaling of the back-flow

As suggested by Simpson (1983), the back-flow mean profiles may be scaled by the maximum mean back-flow velocity (u_N), together with the normal coordinate scaled with the distance from the wall to the maximum (N). The profiles scaled in this way are plotted in figure 23. Simpson (1983) also gives a logarithmic profile valid for $0.02 < y/N < 1.0$ with a constant A involved:

$$\frac{u}{u_N} = A \left[\frac{y}{N} - \ln \left(\frac{y}{N} \right) - 1 \right] - 1. \quad (4.4)$$

The constant A has been given a number of different values in numerous experimental investigations by e.g. Dianat & Castro (1989) and Devenport & Sutton (1991). Thus, the law seems to be of limited value. For comparison, the profile given by equation (4.4) is also shown in figure 23 with $A = 0.3$ as suggested by Simpson (1983). The

collapse of the profiles is poor, and the agreement with equation (4.4) is as bad as in the DNS of a backward-facing step by Le, Moin & Kim (1997).

5. Conclusion

Direct numerical simulations of two turbulent boundary layers have been performed. The flows are subject to slightly different adverse pressure gradients, resulting in two very different flows. One is attached everywhere while the other is separated. Comparison with the earlier simulations shows that the present simulation is well-resolved and has a stronger and larger recirculation region.

In addition to the simulations, a theoretical study was made where the turbulent boundary layer equations are applied to adverse-pressure-gradient (including separated) flows. The theoretical study showed that universal self-similar velocity profiles are possible only in the two extreme cases of zero pressure gradient and zero wall shear stress respectively.

The main conclusions from the theoretical part of the study are as follows:

(i) The near-wall flow can be analysed using the turbulent boundary layer equations even beyond the point of separation. The theory is based on two different velocity scales easily extracted from the parameters of the flow, and thus applicable to turbulence modelling.

(ii) The two velocity scales yield two different velocity profiles, valid in the limits of ZPG and separation respectively. In flows between these asymptotic states, the velocity profiles depend on the Reynolds number and the pressure gradient, both in the viscous sub-layer and the overlap region. In the limit of separation the quadratic and square-root profiles are recovered.

The main conclusions from the analysis of the direct numerical simulations are:

(i) *Near-wall scaling.* The scaling with the local friction velocity close to the wall does not work in the vicinity of separation. By using the pressure-gradient scaling and keeping higher-order terms, the prediction of the velocity profile works surprisingly well far out from the wall, even in the separated region. The agreement between the local analysis and DNS data shows that the flow close to the wall depends primarily on local parameters and not on ‘history effects’. Thus, the main physical reason for the success of the velocity scaling is the dominating dependence of the turbulence on local parameters.

Further out in the boundary layer, in the overlap region, the low Reynolds number makes the comparison with DNS data less valuable. Nevertheless, the DNS data show much better agreement with the overlap profiles derived in the present work than with corresponding law of the wall for a zero-pressure-gradient boundary layer. The comparison was strengthened by using experimental high-Reynolds-number data.

(ii) *Near-wall streaks.* The near-wall streaks are weakened by the adverse pressure gradient, and the spacing in viscous units is increased. In the separated case the streaks vanish at separation. However, the streaks reappear in the region with strong back-flow. Before reattachment the reappearing streaks vanish and after reattachment the streaks start building up again further downstream.

(iii) *Turbulence energy.* The turbulence energy production originating from shear and normal Reynolds stresses are equal in strength. Both contributions are negative at positions upstream of reattachment, which results in destruction of turbulence energy.

Computer time was provided by the Center for Parallel Computers (PDC) at the Royal Institute of Technology (KTH), the National Supercomputer Center in Sweden

(NSC) at Linköping University, and the National Aerospace Laboratory (NAL) in Tokyo. In addition we thank Dr Naoki Hirose and coworkers for the help with implementing the code on the Numerical Wind Tunnel. We would also like to thank Dr Erik Lindborg and Professor Arne Johansson for fruitful discussions and for their valuable comments on the manuscript.

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