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Maximum entanglement of formation for a two-mode Gaussian state over passive operations

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We quantify the maximum amount of entanglement of formation (EoF) that can be achieved by continuous-variable states under passive operations, which we refer to as the *EoF potential*. Focusing, in particular, on two-mode Gaussian states we derive analytical expressions for the EoF potential for specific classes of states. For more general states, we demonstrate that this quantity can be upper bounded by the minimum amount of squeezing needed to synthesize the Gaussian modes, a quantity called squeezing of formation. Our work, thus, provides a link between nonclassicality of quantum states and the nonclassicality of correlations.

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I. INTRODUCTION

Squeezed states [1] have been recognized as a nonclassical resource that can be exploited to improve the performance of several tasks beyond their classical limit [2–4], e.g., enhanced sensitivity of the LIGO detector [5–7], and real-time phase tracking [8,9]. The level of squeezing is characterized by the maximum amount the variance of a single mode falls below the vacuum limit, over all quadrature measurements. Recently, a measure to quantify the squeezing of a multimode state has been proposed, the *squeezing of formation* (SoF) [10], which quantifies the minimum amount of squeezing needed to create a Gaussian state (spread over multiple modes).

Another fundamental resource in quantum information is *entanglement* [11–13]. Entanglement is a property of quantum systems that is manifested as correlations of quantum observables that cannot be classically reproduced [14]. This can lead to the violation of Bell inequalities [15], steering [16], or protocols such as quantum teleportation [17,18], all of which are impossible classically. There is no unique quantifier of entanglement; three examples are entanglement of formation (EoF) [19], logarithmic negativity (LogNeg) [20], and relative entropy of entanglement (REE) [21]. Given that different entanglement measures are, in general, inequivalent to each other [22], the choice of a quantifier depends on the problem that is considered. A typical motivation for using

LogNeg is that, unlike EoF or REE, for example, it is easy to compute.

In the context of continuous-variable (CV) quantum information, the relationship between entanglement and squeezing has been discussed by several authors. Initial discussions appeared in Refs. [23,24] where it was conjectured that nonclassicality (e.g., squeezing) is necessary for entanglement, which was later proven correct [25]. In Ref. [26], Wolf, Eisert, and Plenio proved that under passive operations (assuming access to ancillary vacuum modes) any squeezed state can be transformed into an entangled state with a nonpositive partial transpose with respect to a given partition. This result was recently improved to include all entangled states [27]. The connection between nonclassicality and entanglement has also been addressed under several other notions, e.g., fidelity [28], Schmidt coefficients [29], nonclassical depth [30], quantum discord [30,31], and nonclassicality invariants [32].

The maximum entanglement generated using passive operations, as quantified by LogNeg, has been previously investigated and was shown to be analytically computable for any two-mode Gaussian state [26]. In Ref. [33] the concept of *entanglement potential* was introduced (in the context of characterizing the nonclassicality of a single-mode state) as the maximum entanglement that can be produced through passive linear optics applied on a single-mode nonclassical state and ancillary vacuum modes, measured via LogNeg and REE, for a variety of nonclassical states.

In this work, we extend the analysis of Refs. [26,33], by defining the entanglement potential of a given two-mode Gaussian state as the maximum attainable entanglement through passive linear optics, measured by EoF, and thus

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naming it the *EoF potential*. For certain special cases, we derive closed form solutions for this quantity, and in the more general case, we show that the EoF potential can be upper bounded by the minimum amount of squeezing needed to synthesize the state (SoF).

This paper proceeds as follows. We begin in Sec. II with a brief review regarding Gaussian states, Gaussian operations, and the quantification of squeezing and entanglement. In Sec. III we define the notion of EoF potential between two bosonic modes and demonstrate how it may be bounded from above by the SoF. In Sec. IV we then derive analytical expressions for the EoF potential, while Sec. V concludes with avenues of further research.

II. PRELIMINARIES

A. Gaussian states

Quantized bosonic modes, which are the main focus in this work, are described by CV states [34–37]. Those modes are associated with the quadrature field operators $\hat{x}_j := \hat{a}_j + \hat{a}_j^\dagger$ and $\hat{p}_j := i(\hat{a}_j^\dagger - \hat{a}_j)$, where $\hat{a}_j$ and $\hat{a}_j^\dagger$ are the annihilation and creation operators, respectively, with $[\hat{a}_i, \hat{a}_j^\dagger] = \delta_{ij}$, the Kronecker delta.

Gaussian states are a subclass of CV states that can be fully described by the first two statistical moments (mean value and variance) of the quadrature field operators. For the purposes of this work we can ignore the mean value (fix it for simplicity to zero as it does not contribute to the squeezing or the entanglement of the state) and fully describe the n -mode Gaussian states through a real, symmetric, and positive-definite matrix called the covariance matrix, whose elements are given by $\sigma_{ij} := \frac{1}{2} \langle \{\hat{q}_i, \hat{q}_j\} \rangle$, where $\hat{q} := (\hat{x}_1, \hat{p}_1, \dots, \hat{x}_n, \hat{p}_n)^T$ is the vectorial operator.

Every Gaussian state represented by a covariance matrix σ can be nonuniquely decomposed as [38]

$$\sigma = \pi + \varphi, \quad (1)$$

where π is the covariance matrix of a pure Gaussian state, i.e., $\det(\pi) = 1$, and $\varphi \geq 0$ is a positive-semidefinite matrix representing random correlated displacements in the quadrature fields.

B. Gaussian unitary operations

The action of a Gaussian unitary operation (any unitary operation that transforms a Gaussian state into another Gaussian state) on the covariance matrix σ can be described by the following symplectic transformation Σ :

$$\sigma \mapsto \Sigma \sigma \Sigma^T, \quad (2)$$

where $\Sigma \Omega \Sigma^T = \Omega$, with $\Omega := \bigoplus_{i=1}^n \begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix}$, known as the symplectic form.

Quantum operations can be distinguished as *passive* or *active*, depending on whether they require an external source of energy to realize. From an operational point of view, passive operations are considered “free,” since they can be straightforwardly implemented in the laboratory. On the other hand, active operations are typically more demanding.

FIG. 1. Bloch-Messiah decomposition. A symplectic transformation Σ can be uniquely decomposed into passive (K, L) and active (S) operations.

Any symplectic operation Σ can be decomposed through the *Bloch-Messiah decomposition* [39,40], into a sequence of passive and active operations (see Fig. 1) as follows:

$$\Sigma = K \left[\bigoplus_{i=1}^n S(r_i) \right] L, \quad (3)$$

where K and L are symplectic passive operations, e.g., phase shifts or beam splitters [41], while $S(r_i)$ is a set of single-mode squeezing active operations, defined as

$$S(r_i) := \begin{bmatrix} e^{r_i} & 0 \\ 0 & e^{-r_i} \end{bmatrix}, \quad (4)$$

with $r_i \in \mathbb{R}$. The Bloch-Messiah decomposition will be used in the next section as an intuitive way for quantifying squeezing in pure Gaussian states.

C. Squeezing of formation

Experimentally, squeezing is a sophisticated operation that involves nonlinear processes, and thus practical limitations emerge in our ability to construct certain quantum states. For a single mode, the quantification of squeezing is straightforward, since we have to check only how much the variance of $\hat{x}$ or $\hat{p}$ beats the shot noise (the variance of any quadrature of a vacuum state), which can also be considered as a nonclassicality measure [30,32,33,42,43]. For multimode quantum states, though, where multiple interfering modes can be squeezed, the situation is more complicated, and defining a measure that reflects the “total” amount of squeezing in a state is a nontrivial task.

Given an n -mode pure Gaussian state π , we can write $\pi = \Sigma \Sigma^T$, and since Σ has a nonunique Bloch-Messiah decomposition we can always choose a particular Σ with $L = \mathbb{1}$, i.e., $\pi = K [\bigoplus_{i=1}^n S(r_i) S^T(r_i)] K^T$ (see Fig. 1). Thus, applying the appropriate passive n -mode operation K^T , we end up with a covariance matrix in the following form:

$$\pi \mapsto K^T \pi K = \bigoplus_{i=1}^n S(r_i) S^T(r_i) = \bigoplus_{i=1}^n \begin{bmatrix} e^{2r_i} & 0 \\ 0 & e^{-2r_i} \end{bmatrix}. \quad (5)$$

This means that the pure state π can be decomposed into n uncorrelated pure squeezed states through the passive operation K^T . The $2n$ eigenvalues λ_i of this covariance matrix come in reciprocal pairs, so if we arrange them in an increasing order, i.e., $\lambda_i^\uparrow := \lambda_1 \leq \lambda_2 \leq \dots \leq \lambda_{2n}$, we can fully characterize the eigenspectrum of π through the first half of them. The squeezing of this multimode pure state π can be characterized through the following function [10]:

$$S(\pi) := -\frac{1}{2} \sum_{i=1}^n \ln[\lambda_i^\uparrow(\pi)] = \sum_{i=1}^n |r_i|, \quad (6)$$

which gives the sum of the absolute squeezing parameters of each mode for a pure state in the Bloch-Messiah decomposition.

Squeezing of formation (SoF) for an arbitrary state σ is defined [10] as the convex-roof extension of Eq. (6),

$$S(\sigma) := \inf_{\pi} \{S(\pi) \mid \sigma = \pi + \varphi\}, \quad (7)$$

and it quantifies the least amount of squeezing of the pure state π on which we can apply random correlated displacements φ to create the state σ . The merit of this measure is that it rigorously characterizes the amount of squeezing in a state, since the function $S(\sigma)$ satisfies properties such as convexity and continuity [10].

Remark 1. From the the Bloch-Messiah decomposition it follows that two states with the same SoF cannot in general be transformed under passive operations into one another. Consider, for example, two pure states with the same SoF. The symplectic operation applied onto the vacuum modes (for each state) has, in general, different local squeezing parameters r_i , and thus subsequent passive operations cannot make the states identical. For example, with current technology the highest amount of single-mode squeezing has a parameter of $r \sim 1.7$ (or ~ 15 dB) [44]. So, according to Eq. (6), a given pure two-mode state of $S(\sigma) \sim 2$ can be constructed only if the squeezing is distributed such that $|r_1| + |r_2| \sim 2$, but each mode is not squeezed more than the (current) limit, such that $|r_i| \leq 1.7$.

D. Entanglement of formation

Entanglement of formation (EoF) is defined as the convex-roof extension of the entropy of entanglement [19] and quantifies the entanglement in terms of the entropy of entanglement of the least entangled state needed to prepare it (under local operations and classical communication).

For two-mode Gaussian states EoF is given by [45–49]

$$\mathcal{E}(\sigma) := \inf_{\pi} \{\mathcal{E}(\pi) \mid \sigma = \pi + \varphi\}, \quad (8)$$

where $\mathcal{E}(\pi)$ is the *entropy of entanglement* of the bipartite pure state π . $\mathcal{E}(\pi)$ is defined as the von Neumann entropy of the reduced state and given by [50,51]

$$\mathcal{E}(\pi) := \begin{cases} h[\nu_-(\pi^\Gamma)] & \text{for } \nu_-(\pi^\Gamma) < 1 \\ 0 & \text{for } \nu_-(\pi^\Gamma) \geq 1 \end{cases}, \quad (9)$$

where $\nu_-(\pi^\Gamma)$ is the lowest (of the two) symplectic eigenvalue of the partially transposed pure state π , and $h(x)$ is the

FIG. 2. Passive operations K_j applied on a two-mode Gaussian state σ and n ancillary vacuum modes. The final state σ_j is the reduced two-mode Gaussian state that remains after tracing out the last n modes.

auxiliary function defined as

$$h(x) := \frac{(1+x)^2}{4x} \log_2 \left[\frac{(1+x)^2}{4x} \right] - \frac{(1-x)^2}{4x} \log_2 \left[\frac{(1-x)^2}{4x} \right]. \quad (10)$$

Remark 2. Equation (8) technically defines the Gaussian EoF, which for multimode Gaussian states, in general, is an upper bound to the EoF, but for two-mode Gaussian states the two measures coincide [52,53]. For the rest of the work we focus only on two-mode Gaussian states.

III. ENTANGLEMENT POTENTIAL

In this section, we introduce the concept of entanglement potential using EoF as the entanglement measure, and we present the main result of this work in Proposition 1, where we upper bound the entanglement potential for any two-mode Gaussian state.

A. Definition of EoF potential

Consider a two-mode Gaussian state with covariance matrix σ and access to n ancillary vacuum modes and $(n+2)$ -mode passive operations K_j . *Entanglement of formation potential* (EoF potential) quantifies the maximum attainable EoF of a state σ as follows:

$$\mathcal{P}(\sigma) := \sup_j \{ \mathcal{E}(\sigma_j) \mid \sigma_j = \text{tr}_n [K_j(\sigma \oplus \mathbb{1}_n) K_j^T] \}, \quad (11)$$

where tr_n denotes the partial trace over the last n modes (see Fig. 2). The introduction of the ancillary vacuum modes in the definition of the EoF potential might seem redundant at first sight, but an example where those extra modes can indeed be useful can be found in Sec. IV A. Also, note that the definition given in Eq. (11) for the EoF potential can be modified for any other entanglement measure or monotone. For instance, based on this context the proposition 2 of Ref. [26] corresponds to the LogNeg potential.

B. Bounds of EoF potential

By construction, the EoF of any state σ is a lower bound to the EoF potential:

$$\mathcal{E}(\sigma) \leq \mathcal{P}(\sigma). \quad (12)$$

For two-mode Gaussian states we can always numerically estimate the value of $\mathcal{E}(\sigma)$, and for special classes we can also achieve analytical expressions [45–50]. A more interesting bound to the EoF potential would be an upper bound, which we derive below.

Proposition 1. For an arbitrary two-mode Gaussian state σ , the EoF potential is upper bounded as follows:

$$\mathcal{P}(\sigma) \leq h[e^{-\mathcal{S}(\sigma)}], \quad (13)$$

where $\mathcal{S}(\sigma)$ is the SoF of σ .

Proof. The EoF potential can be written as

$$\begin{aligned} \mathcal{P}(\sigma) &:= \sup_j \{ \mathcal{E}(\sigma_j) \mid \sigma_j = \text{tr}_n[K_j(\sigma \oplus \mathbb{1}_n)K_j^T] \} \\ &= \sup_j \inf_{\pi_j} \{ \mathcal{E}(\pi_j) \mid \sigma_j = \pi_j + \varphi_j \} \\ &= \sup_j \mathcal{E}(\pi_{e,j}), \end{aligned} \quad (14)$$

where $\pi_{e,j}$ is the covariance matrix of the pure state that achieves the $\inf_{\pi_j} \mathcal{E}(\pi_j)$. Based on Refs. [26,27], for any pure state π we have

$$v_-(\pi^\Gamma) \geq \sqrt{\lambda_1^\uparrow(\pi)\lambda_2^\uparrow(\pi)} \Rightarrow h[v_-(\pi^\Gamma)] \leq h[e^{-\mathcal{S}(\pi)}], \quad (15)$$

and for pure states we can always find a passive operation (without introducing ancillary vacuum modes) that saturates the above inequality, so for a generic pure state π we have

$$\sup_j \mathcal{E}(\pi_j) = h[e^{-\mathcal{S}(\pi)}], \quad (16)$$

where the right-hand side does not depend on the operation K_j . Thus, the EoF potential in Eq. (14) takes the following form:

$$\mathcal{P}(\sigma) = h[e^{-\mathcal{S}(\pi_{e,j})}]. \quad (17)$$

A passive operation cannot affect the SoF of a state, so

$$\mathcal{S}(\sigma_j) = \inf_{\pi_j} \mathcal{S}(\pi_j) = \mathcal{S}(\pi_{s,j}) = \mathcal{S}(\sigma), \quad (18)$$

where $\pi_{s,j}$ is the covariance matrix of the state that achieves the $\inf_{\pi_j} \mathcal{S}(\pi_j)$. For any passive operation K_j we have

$$\mathcal{E}(\pi_{e,j}) \leq \mathcal{E}(\pi_{s,j}) \Rightarrow \sup_j \mathcal{E}(\pi_{e,j}) \leq \sup_j \mathcal{E}(\pi_{s,j}), \quad (19)$$

and, so, we finally get

$$\mathcal{P}(\sigma) \leq h[e^{-\mathcal{S}(\sigma)}], \quad (20)$$

which completes the proof. ■

In order to calculate the upper bound in Eq. (13) we need to first calculate $\mathcal{S}(\sigma)$. In Ref. [10] a numerical method was derived for the estimation of $\mathcal{S}(\sigma)$, along with some upper and lower bounds. In the section below, we derive analytical expressions for some specific classes of two-mode Gaussian states.

Remark 3. Regardless of how each mode is individually squeezed, EoF potential is related to the overall squeezing, quantified by SoF. Take, for example, a pure state π_1 that consists of a position-quadrature squeezed vacuum ($r_1 = 2$) and a nonsqueezed vacuum ($r_2 = 0$), and another state π_2 that consists of two squeezed vacuum modes, one in the position

quadrature ($r_1 = 1$) and the other in the momentum quadrature ($r_2 = -1$). Those two states have the exact same amount of SoF, since based on Eq. (6) we have $\mathcal{S}(\pi_1) = |2| + |0| = 2$ and $\mathcal{S}(\pi_2) = |1| + |-1| = 2$. The EoF for the two states is also equal, which can be seen as follows. We apply to both states a balanced (50:50) beam splitter which (as a passive operation) keeps the SoF constant. Then, through local unitary operations (both passive and active) which keep the EoF constant, we can end up with the exact same covariance matrix (called the standard form of the covariance matrix [54,55]), so $\mathcal{E}(\pi_1) = \mathcal{E}(\pi_2)$.

IV. EXACT VALUE FOR EOF POTENTIAL IN SPECIAL CASES

In this section, we derive analytical expressions for the SoF of specific classes of two-mode Gaussian states, which in conjunction with the corresponding expressions for the EoF, give a closed formula for the EoF potential.

Let us reorder the vectorial operator into $\hat{q}' := (\hat{x}_1, \hat{x}_2, \hat{p}_1, \hat{p}_2)^T$, so the covariance matrix of a two-mode Gaussian state takes the following form:

$$\sigma = \begin{bmatrix} \langle x_1^2 \rangle & \langle x_1 x_2 \rangle & \frac{1}{2} \langle \{x_1, p_1\} \rangle & \langle x_1 p_2 \rangle \\ \langle x_2 x_1 \rangle & \langle x_2^2 \rangle & \langle x_2 p_1 \rangle & \frac{1}{2} \langle \{x_2, p_2\} \rangle \\ \frac{1}{2} \langle \{p_1, x_1\} \rangle & \langle p_1 x_2 \rangle & \langle p_1^2 \rangle & \langle p_1 p_2 \rangle \\ \langle p_2 x_1 \rangle & \frac{1}{2} \langle \{p_2, x_2\} \rangle & \langle p_2 p_1 \rangle & \langle p_2^2 \rangle \end{bmatrix}. \quad (21)$$

Consider a state with no cross quadrature correlations,¹ i.e., $\langle \hat{x}_i \hat{p}_j \rangle = \langle \hat{p}_i \hat{x}_j \rangle = 0, \forall \{i, j\}$, so Eq. (21) becomes

$$\sigma = \begin{bmatrix} a_1 & c_1 \\ c_1 & b_1 \end{bmatrix} \oplus \begin{bmatrix} a_2 & c_2 \\ c_2 & b_2 \end{bmatrix} = c_x \oplus c_p, \quad (22)$$

where we require that $a_i b_i - c_i \geq 1$ for the state to be physical. In order to simplify the calculation of SoF for states in the form of Eq. (22) we show below that instead of minimizing over all pure states we can restrict the optimization over only a subset of them.

It has been shown in Refs. [45,57] that a two-mode Gaussian state is pure if and only if its covariance matrix has the following form:

$$\pi(z, y) = \begin{bmatrix} z & zy \\ yz & yzy + z^{-1} \end{bmatrix}, \quad (23)$$

where $z = z^T > 0$ and $y = y^T$ are real and symmetric 2×2 submatrices.

Proposition 2. Among all pure two-mode Gaussian states $\pi(z, y)$, squeezing of formation is minimized by pure states of the form $\pi(z, 0)$:

$$\mathcal{S}[\pi(z, y)] \geq \mathcal{S}[\pi(z, 0)]. \quad (24)$$

¹This is not the most general class of states, since using only passive operations we cannot always end up to this type of covariance matrix, but it is an experimentally relevant class (see Ref. [56] for a method to verify whether a state has no cross quadrature correlations has been constructed by some of us).

Proof. Based on Eq. (6), SoF for a state $\pi(\mathbf{z}, \mathbf{y})$ is equal or larger than that of a state $\pi(\mathbf{z}, 0)$ if we have

$$\lambda_i^\uparrow[\pi(\mathbf{z}, \mathbf{y})] \leq \lambda_i^\uparrow[\pi(\mathbf{z}, 0)], \quad \text{for } i = \{1, 2\}, \quad (25)$$

where $\lambda_i^\uparrow[\pi(\mathbf{z}, \mathbf{y})]$ are the eigenvalues of each state in an increasing order. Then, for a given orthogonal projection $\Pi = (1, 1, 0, 0)^T$ on $\pi(\mathbf{z}, \mathbf{y})$,

$$\mathbf{z} = \Pi^T \pi(\mathbf{z}, \mathbf{y}) \Pi, \quad (26)$$

the *Cauchy interlacing theorem* (Theorem 4.3.17 in Ref. [58]) imposes that

$$\lambda_i^\uparrow[\pi(\mathbf{z}, \mathbf{y})] \leq \lambda_i^\uparrow(\mathbf{z}) = \lambda_i^\uparrow[\pi(\mathbf{z}, 0)], \quad (27)$$

which completes the proof. ■

Based on the above proposition, for states in the form of Eq. (22) the SoF needs to be minimized over only pure states of the form $\pi(\mathbf{z}, 0)$, and due to Eq. (1) the constraint $\sigma \geq \pi$ becomes $\mathbf{c}_p^{-1} \leq \mathbf{z} \leq \mathbf{c}_x$:

$$\mathcal{S}[\sigma = \mathbf{c}_x \oplus \mathbf{c}_p] := \inf_{\mathbf{z}} \{ \mathcal{S}[\pi(\mathbf{z}, 0)] \mid \mathbf{c}_p^{-1} \leq \mathbf{z} \leq \mathbf{c}_x \}. \quad (28)$$

Below we present the analytical expressions for two specific classes of two-mode Gaussian states.

A. Symmetric states

Symmetric states have quadratures with equal variance but (in general) different correlations in $\hat{x}$ and $\hat{p}$. The covariance matrix of symmetric states is given by

$$\sigma_{\text{sym}} = \begin{bmatrix} a & c_1 \\ c_1 & a \end{bmatrix} \oplus \begin{bmatrix} a & c_2 \\ c_2 & a \end{bmatrix}. \quad (29)$$

Interfering the two modes on a balanced beam splitter, we end up with the following covariance matrix:

$$\begin{bmatrix} a+c_1 & 0 \\ 0 & a-c_1 \end{bmatrix} \oplus \begin{bmatrix} a+c_2 & 0 \\ 0 & a-c_2 \end{bmatrix}, \quad (30)$$

which represents two uncorrelated modes, and the constraint $\mathbf{c}_p^{-1} \leq \mathbf{z} \leq \mathbf{c}_x$ takes the form

$$\begin{bmatrix} \frac{1}{a+c_2} & 0 \\ 0 & \frac{1}{a-c_2} \end{bmatrix} \leq \mathbf{z} \leq \begin{bmatrix} a+c_1 & 0 \\ 0 & a-c_1 \end{bmatrix}. \quad (31)$$

Squeezing of formation, then, is equal to

$$\mathcal{S}(\sigma_{\text{sym}}) = -\ln(\mu_+ \mu_-), \quad (32)$$

where $\mu_{\pm} = \min\{1, \sqrt{a \pm c_1}, \sqrt{a \pm c_2}\}$. The EoF of symmetric states is given by [59]

$$\mathcal{E}(\sigma_{\text{sym}}) = \begin{cases} h\left(\sqrt{\lambda_1^\uparrow \lambda_2^\uparrow}\right) & \text{for } \lambda_1^\uparrow \lambda_2^\uparrow < 1, \\ 0 & \text{for } \lambda_1^\uparrow \lambda_2^\uparrow \geq 1 \end{cases}, \quad (33)$$

where $\lambda_1^\uparrow$ and $\lambda_2^\uparrow$ are the two lowest eigenvalues of σ_{sym} in an increasing order, i.e., $\lambda_1^\uparrow \leq \lambda_2^\uparrow$. When the state σ_{sym} is classical, i.e., $\lambda_1^\uparrow \geq 1$, or entangled with $\lambda_2^\uparrow < 1$, we get

$$\mathcal{E}(\sigma_{\text{sym}}) = h[e^{-\mathcal{S}(\sigma_{\text{sym}})}], \quad (34)$$

and thus the lower bound in Eq. (12) coincides with the upper bound in Eq. (13). However, for states (separable or entangled) with $\lambda_1^\uparrow < 1 \leq \lambda_2^\uparrow$, we get $\mathcal{E}(\sigma_{\text{sym}}) < h[e^{-\mathcal{S}(\sigma_{\text{sym}})}]$,

which does not saturate the upper bound. In order to achieve the upper bound, we can perform the following operation:

$$\sigma' = \text{tr}_3[K(\sigma_{\text{sym}} \oplus \mathbb{1})K^T], \quad (35)$$

with $K = [B(\pi/4) \oplus \mathbb{1}][\mathbb{1} \oplus B(\pi/2)][B(\pi/4) \oplus \mathbb{1}]$. $B(\theta) = \exp[\theta(\hat{a}^\dagger \hat{b} - \hat{a} \hat{b}^\dagger)]$ is a beam-splitter operation, with $\hat{a}$ and $\hat{b}$ denoting the annihilation operators of each mode, respectively. Practically, in Eq. (35) we first apply a balanced beam splitter on the first two modes in order to diagonalize the covariance matrix, corresponding to two uncorrelated modes, one thermal and one squeezed. Without losing generality we assume that the thermal mode is the second one. Then, the ancilla vacuum is swapped with the thermal mode, and a second balanced beam splitter is applied to increase the entanglement. Finally, the operation tr_3 traces out the third mode. At the end, the entanglement of the state σ' is given by

$$\mathcal{E}(\sigma') = h[e^{-\mathcal{S}(\sigma_{\text{sym}})}], \quad (36)$$

which coincides with the upper bound [Eq. (13)], and thus the EoF potential of symmetric states is given by

$$\mathcal{P}(\sigma_{\text{sym}}) = h(\mu_+ \mu_-). \quad (37)$$

B. Balanced correlated states

Balanced correlated states have an equal amount of correlations in $\hat{x}$ and $\hat{p}$, i.e., $c_1 = -c_2 = c > 0$, as well as quadratures with the same variance in $\hat{x}$ and $\hat{p}$, i.e., $a_1 = a_2 = a$, and $b_1 = b_2 = b$. Their covariance matrix has the following form:

$$\sigma_{\text{bc}} = \begin{bmatrix} a & c \\ c & b \end{bmatrix} \oplus \begin{bmatrix} a & -c \\ -c & b \end{bmatrix}. \quad (38)$$

These states correspond to the output of a two-mode squeezed state passing through two independent phase-invariant Gaussian channels, and they are typically encountered in quantum communication protocols, e.g., quantum teleportation [17] and quantum key distribution [60]. If $1 - a - b + ab \geq c^2$ all the eigenvalues of σ_{bc} are greater or equal to one, and thus the state is classical and SoF vanishes.

Unlike symmetric states, these states cannot be brought into a diagonal form by a passive transformation. In Appendix A we show that in this case the optimal $\mathbf{z}$ is given by

$$\mathbf{z}_{\text{opt}} = \frac{\lambda_+}{2} \begin{bmatrix} 1 & 1 \\ 1 & 1 \end{bmatrix} + \frac{\lambda_-}{2} \begin{bmatrix} 1 & -1 \\ -1 & 1 \end{bmatrix}, \quad (39)$$

where λ_- and λ_+ are the two eigenvalues of $\mathbf{z}_{\text{opt}}$, given by

$$\lambda_{\pm} = \frac{1}{\lambda_{\mp}} = \frac{a + b + 2c}{1 + ab - c^2 + \sqrt{(1 - ab + c^2)^2 - (a - b)^2}}, \quad (40)$$

and the SoF is

$$\mathcal{S}(\sigma_{\text{bc}}) = \ln \lambda_+. \quad (41)$$

The EoF for balanced correlated states was calculated in Ref. [50] (where the name ‘‘GMEM’’ was given to the same type of states), but a simpler expression can be found in Refs. [48,49]. As we show in Appendix B, the EoF is equal to

$$\mathcal{E}(\sigma_{\text{bc}}) = h[e^{-\mathcal{S}(\sigma_{\text{bc}})}] = h(\lambda_-), \quad (42)$$

and, since the lower bound in Eq. (12) coincides with the upper bound in Eq. (13), the EoF potential for balanced correlated states is given by

$$\mathcal{P}(\sigma_{bc}) = h(\lambda_-). \quad (43)$$

Thus, the entanglement of any balanced correlated state achieves by construction its EoF potential, and no further passive operation is needed.

V. DISCUSSION

In continuous-variable optics, the class of operations that is typically considered the most simple to realize is passive linear operations. In this work we ask, given two-mode Gaussian states, what is the maximum amount of entanglement (as quantified by entanglement of formation) that we can synthesize using such operations? We named this quantity the EoF potential and analytically computed it for certain special cases of two-mode Gaussian states. For more general states, we demonstrated that EoF potential can be bounded from above given the squeezing of formation of the same state—the amount of squeezing needed to synthesize these modes. This, thus, presents another interesting connection between nonclassicality of quantum states and the nonclassicality of correlations in the Gaussian regime.

There are a number of interesting future directions. One immediate question is the tightness of the bounds derived; another is to what extent such relations can be generalized to other measures of quantum correlations and nonclassicality of quantum states. This would become especially pertinent should we consider non-Gaussian states, whereby existing measures of nonclassicality have already been defined from the perspectives of metrological advantage and nonequilibrium energy [42,43,61]. Such directions could well shed light on potential connections to entanglement distillation, where a no-go theorem prevents distillation through local Gaussian operations [62–64].

Note added. Recently, we learnt about a similar paper [65], where the authors bound EoF using a nonclassicality measure called *monotone of total noise*.

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APPENDIX A: SoF FOR BALANCED CORRELATED STATES

In this Appendix, we compute the SoF for a balanced correlated state [defined in Eq. (38)] through Eq. (28). Following the analysis of Ref. [45], we set

$$\mathbf{c}_x := \begin{bmatrix} x_0 + x_1 & x_2 \\ x_2 & x_0 - x_1 \end{bmatrix}, \quad \mathbf{c}_p^{-1} := \begin{bmatrix} p_0 + p_1 & p_2 \\ p_2 & p_0 - p_1 \end{bmatrix} \quad (A1)$$

and

$$\mathbf{z} := \begin{bmatrix} z_0 + z_1 & z_2 \\ z_2 & z_0 - z_1 \end{bmatrix}, \quad (A2)$$

and we represent the matrices $\mathbf{z}$, $\mathbf{c}_x$, and $\mathbf{c}_p^{-1}$, as points in three dimensions with coordinates, e.g., (x_1, x_2, x_0) . With this representation, and given the constraint $\mathbf{c}_p^{-1} \leq \mathbf{z} \leq \mathbf{c}_x$, the coordinates of $\mathbf{z}$ must lie within the intersection of two 45° vertical cones with vertices corresponding to $\mathbf{c}_x$ and $\mathbf{c}_p^{-1}$. For states where both $\mathbf{c}_x$ and $\mathbf{c}_p$ have one eigenvalue greater than one and one eigenvalue less than one (σ_{bc} falls in this category), the optimal $\mathbf{z}$ must also lie on the surface of both these cones. This surface is parameterized by $\det(\mathbf{z} - \mathbf{c}_x) = 0$ and $\det(\mathbf{c}_p^{-1} - \mathbf{z}) = 0$. With these two constraints, the problem of quantifying the SoF reduces to finding the optimal $\mathbf{z}$, restricted to the ellipse defined by the intersection of the two surfaces of the cones.

The coordinates of this ellipse can be parametrized by the angle ϕ as follows:

$$z_1(\phi) = \frac{x_1 + p_1}{2} + r_1 \cos \gamma \sin \phi - r_2 \sin \gamma \cos \phi, \quad (A3a)$$

$$z_2(\phi) = \frac{x_2 + p_2}{2} + r_1 \sin \gamma \sin \phi + r_2 \cos \gamma \cos \phi, \quad (A3b)$$

$$z_0(\phi) = x_0 - \sqrt{(x_1 - z_1)^2 + (x_2 - z_2)^2}, \quad (A3c)$$

where $\gamma := \arctan(c_2/c_1)$, $c_i := (a_i - b_i)/2$, $r_1 := c_0$, and $r_2 := \sqrt{c_0^2 - (c_1^2 + c_2^2)}$. The SoF of $\mathbf{z}$ is $\mathcal{S}[\pi(\mathbf{z}, 0)] = \frac{1}{2} \log \frac{\lambda_+}{\lambda_-}$, where

$$\lambda_{\pm} = z_0 \pm \sqrt{z_1^2 + z_2^2} = z_0 \left(1 \pm \sqrt{\frac{z_1^2 + z_2^2}{z_0^2}} \right) \quad (A4)$$

are the two eigenvalues of $\mathbf{z}$. Minimizing $\mathcal{S}[\pi(\mathbf{z}, 0)]$ is equivalent to minimizing $(z_1^2 + z_2^2)/z_0^2$, so we need to find the angle ϕ that minimizes $(z_1^2 + z_2^2)/z_0^2$. For an arbitrary $\mathbf{c}_x$ and $\mathbf{c}_p^{-1}$, this involves solving a transcendental equation which does not have an analytical solution. However, for the balance correlated state, this minimization can be done analytically, and through long but straightforward computations, we find that $(z_1^2 + z_2^2)/z_0^2$ is minimized when

$$z_0 = \frac{\lambda_+ + \lambda_-}{2}, \quad z_1 = \frac{\lambda_- - \lambda_+}{2}, \quad \text{and} \quad z_2 = 0, \quad (A5)$$

with

$$\lambda_{\pm} = \frac{1}{\lambda_{\mp}} = \frac{a + b + 2c}{1 + ab - c^2 + \sqrt{(1 - ab + c^2)^2 - (a - b)^2}}. \quad (A6)$$

APPENDIX B: PROOF OF Eq. (42)

Based on Refs. [48,49] the EoF for entangled balanced correlated states is given by

$$\mathcal{E}(\sigma_{bc}) = \cosh^2 r_o \log_2(\cosh^2 r_o) - \sinh^2 r_o \log_2(\sinh^2 r_o), \quad (\text{B1})$$

where

$$r_o = \frac{1}{4} \ln \left[\frac{2\kappa^2 + \tau_1 \tau_2 - 2\sqrt{\kappa^2(\kappa^2 + \tau_1 \tau_2)}}{\tau_2^2} \right], \quad (\text{B2})$$

$$\cosh^2 r_o = \frac{(1 + e^{-2r_o})^2}{4e^{-2r_o}} = \frac{(1 + \lambda_-)^2}{4\lambda_-} \implies e^{-2r_o} = \lambda_- \implies e^{-4r_o} = \lambda_-^2. \quad (\text{B5})$$

Consider

$$\lambda_-^2 e^{4r_o} = \frac{[2\kappa^2 + \tau_1 \tau_2 - 2\sqrt{\kappa^2(\kappa^2 + \tau_1 \tau_2)}][2\kappa^2 + \tau_1 \tau_2 + 2\sqrt{\kappa^2 + \tau_1 \tau_2}]}{\tau_1^2 \tau_2^2} \quad (\text{B6a})$$

$$= \frac{(2\kappa^2 + \tau_1 \tau_2)^2 - 4\kappa^2(\kappa^2 + \tau_1 \tau_2)}{\tau_1^2 \tau_2^2} \quad (\text{B6b})$$

$$= 1. \quad (\text{B6c})$$

Equation (B6b) holds only when $\kappa \geq 0$, which is true for all quantum states, which completes the proof.

with

$$\kappa := ab - c^2 + 1, \quad (\text{B3a})$$

$$\tau_1 := 2c + a + b, \quad (\text{B3b})$$

$$\tau_2 := 2c - a - b. \quad (\text{B3c})$$

The parameter λ_- in Eq. (40) can analogously be written as

$$\lambda_- = \frac{\kappa + \sqrt{\kappa^2 + \tau_1 \tau_2}}{\tau_1}. \quad (\text{B4})$$

In order to prove Eq. (42) we need to show that

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