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Eco-Modular Product Architecture Identification and Assessment for Product Recovery

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Abstract

In order to improve the efficiency of disassembly and product recovery of an abandoned product at the end-of-life stage, it is essential to develop modular product architecture by considering manufacturing and recovering processes in early product design stage. In this paper, a novel concept of a design methodology is introduced to develop eco-modular product architecture and assess the modularity of the architecture from the viewpoint of product recovery. Eco-modular product architecture contributes to enhancing product recovery processes by recycling and reusing modules without full disassembly at component or material levels. It leads to less consumption of natural resources and less landfill damage to the environment. Three sustainable modular drivers, namely, interface complexity, material similarity, and lifespan similarity, are introduced to reconstruct the modular architecture of commercial products into the eco-modular architecture. Alternatives of modular architectures are identified by Markov Cluster Algorithm based on these sustainable modular drivers and physical interconnections of the components of product architecture. To select the eco-modular architecture from these alternatives, we propose modularity assessment metrics to identify independent interactions between modules and the degrees of similarity within each module. To demonstrate the effectiveness of the proposed methodology, a case study is performed with a coffee maker.

Keywords: Eco-module, Markov Cluster Algorithm, Modularity assessment, Product architecture, Product recovery

1 Introduction

As governments become more stringent concerning environment issues and take more interest in sustainability, manufacturers are also required to meet environmental legislations and produce eco-friendly products (Ramani et al. 2010; Ilgin and Gupta 2010). However, with the rapid development of technology, high-end products, especially electronic products, incite customers to purchase goods without thinking of the impact it will have on the environment. The technology push strategy of a company results in mass production of new products and frequent product replacements by the customers. The mass production for new products increases the impact on environmental pollution during the manufacturing process. Although a product is still good enough to use, when the product is discarded, the product lifecycle shortens. This has a negative effect on the

1 environment as the landfill rate heightens. Therefore, product recovery must be considered in the early product
2 design stage to minimize the landfill rate.

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4 To recover products in the end-of-life (EOL) stage, product architecture development is necessary to
5 facilitate the disassembly process. If product architecture is complex at the disassembly stage, individual parts of
6 the product can be difficult to retrieve and can increase the chances for damage (Kim et al. 2015; Behdad et al.
7 2014). In this sense, modular product design should be one of the most important considerations to improve
8 disassemblability for the product recovery. Modular architecture mainly contributes to diminishing the
9 complexity of the product architecture by identifying physical chunks (Pimmler and Eppinger 1994; Ulrich and
10 Eppinger 2008). As the modular architecture has a higher number of internal couplings within the module and
11 less external couplings between modules, the modular product can be maintained or replaced effectively by
12 substituting the modules (Ulrich 1995; Chiriac et al. 2011). However, most of the modules in previous research
13 are generated based on the functional or physical relationships of the product architecture (Yu et al. 2007;
14 Thebeau 2001; Du et al. 2014), and predefined as module variants by using optimization approaches (Du et al.
15 2014; Kwak et al. 2009; Fujita and Yoshida 2004; Yigit et al. ; Moon et al. 2014), market-based decision
16 making approaches (Moon and McAdams 2012) or data mining approaches (Moon et al. 2010). Also, most of
17 the previous modular product designs have focused more on clustering modules to maximize internal coupling
18 and minimize external coupling without considering product recovery processes. Although the existing modules
19 are well-defined and effective for manufacturing, these modules would not be easy to disassemble at the product
20 recovery stage. If components with different materials and lifespans are mixed in a module, disassembly
21 operators need to make more effort to fully disassemble the module into components or materials (Otto and
22 Wood 2001).

23
24 To develop modular architecture from the viewpoint of the product recovery, we introduce a novel design
25 methodology to extend existing research from modular product design to eco-modular product design. The
26 objective of this research is to determine eco-modular architecture and assess its degree of modularity by
27 considering the product recovery based on sustainable modular drivers. The sustainable modular drivers consist
28 of interface complexity, material similarity, and lifespan similarity. With the sustainable modular drivers,
29 Markov Cluster Algorithm is applied to identify eco-modules, which is a chunk of components with similar
30 materials and/or lifespans. Also, a novel modularity assessment method is proposed to quantify the degree of
31 modularity of the eco-modular architecture by using module independence and module similarity metrics. The
32 module independence metric indicates the degree of independence by assessing interface complexity between
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1 modules, while the module similarity metric indicates the degree of similarity within modules. Based on the
2 results from the metrics, the eco-modular architecture can be selected.

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4 The subsequent sections of this paper are structured as follows. Section 2 reviews literature related to
5 modular product architecture design and assessment, and product design for product recovery. Section 3
6 describes the proposed methodology to guide eco-modular architecture design. Section 4 provides a case study
7 to demonstrate the effectiveness of the proposed methodology and section 5 presents the conclusion, limitations
8 and future work of this paper.
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13 **2 Literature review**

14 **2.1 Modular product design and its assessment**

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16 In product recovery, modular product design is one of the solutions to improve disassemblability and
17 manage the efficiency and difficulty of the disassembly. The modularity has been developed to improve
18 manufacturing production (Jose and Tollenaere 2005), maintainability, serviceability (Otto and Wood 2001),
19 and disassemblability for the end of product lifecycle (Newcomb et al. 1998). In order to identify the modules,
20 product architecture was largely represented by matrix and graph based representations. Matrix-based
21 representation makes up rows, columns and matrix elements. The rows and columns are developed by
22 component lists, and the matrix elements represent functional or physical relationships between the components.
23 The matrix elements have a binary value to show the connectivity between components or weighted value to
24 show the strength of connectivity. As for the product information to be used for modularization, physical
25 structure information and functional information were mainly considered. Firstly, physical relationships are
26 fundamentally used to figure out modules. The design structure matrix (DSM) is a popular method to represent
27 the physical relationships between components. Yu et al. (2007) considered the physical relationships using the
28 DSM method and applied minimum description length (MDL)-based clustering method with a genetic algorithm
29 (GA) to identify modules. The feature of the clustering method is to allow bus modules and overlapping
30 modules. Yan et al. (2012) utilized the DSM to establish the correlation between the components based on the
31 strength of interaction and then identified modules with the kernel-based fuzzy c-means algorithm. Secondly,
32 with regard to functional information, Helmer et al. (2010) used information values about types of interactions,
33 such as structural, spatial, signal, material, and energy, from the research of Pimmler and Eppinger (1994) and
34 Sosa et al. (2003). Chun-Che and Kusiak (1998) interpreted three types of modularity, namely, component
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1 swapping, component sharing and bus modularity, and determined modules based on the decomposition
2 approach and three axioms related to the three types of modularity. To identify the three modules, physical
3 interactions and suitability values were considered in the DSM. The minimum description length (MDL)-based
4 DSM clustering was utilized to cluster modules based on the types of functional interactions. Asikoglu and
5 Simpson (2012) measured the weighted modular complexity score (wMCS) according to different types of
6 interfaces. Then, Jung et al. (2014) used the wMCS and the GA to improve the modularity of products. Heuristic
7 methods are also applied to modularize functional structures based on shared and unique functions (Dahmus et
8 al. 2001; Krause et al. 2014; Hölttä and Otto 2005). By utilizing the heuristic method, a group that shares similar
9 functions and flows should be clustered in a single module, and components with unique functions can be
10 grouped in a module. Erixon (1998) introduced the modular function deployment (MFD) which heuristically
11 determines modules by maximizing similarity technical solutions in terms of module drivers.

12 Aforementioned methods developed modules based on either the physical relationship or the functional
13 relationship. To overcome this issue, Borjesson and Hölttä-Otto (2014) suggested a new modularization
14 algorithm to consider both the DSM for the physical relationships and the modular function deployment (MFD)
15 for functions. Meng et al. (2007) proposed a multi-objective combinatorial optimization problem for module
16 identification by using the GA. To consider module configurability, these kinds of information were analysed
17 and used as follows: the simultaneous use of module alterability and module manufacturing efficiency; and both
18 physical and functional information, such as functional relationships and structural relationships.

19 After identifying various module candidates by considering various information, modularity assessment of
20 the module candidates was necessary to evaluate whether the modules were well-clustered to meet designers'
21 intent or not. Fixson (2005) introduced product architecture assessment with a function-component allocation
22 scheme to distinguish modular or integral architectures; interface characteristics, such as type, reversibility, and
23 standardization were also measured. Chiriac et al. (2011) analysed modular product architecture to determine
24 the degree of modularity and the level of system granularity. Newcomb et al. (1998) developed similarity
25 metrics to assess modularity for the EOL stage by comparing the correspondence of the inner module's
26 connection between more than two product architectures for the product lifecycle. Moreover, the interface
27 design related to compatibility and interchangeability was significantly considered when the module was
28 defined. Well-designed interfaces can minimize complexity and uncertainty in disassembly operation. Pimmler
29 and Eppinger (1994) measured the degree of generic interaction by using categories of energy, spatial,
30 information, and materials. Fixson (2005) additionally analysed the reversibility of interfaces for product

1 changes during product lifecycle, such as upgrades, adaptation, wear, or reuse, together with interface
2 standardization. Dobberfuhl and Lange (2009) proposed a modular complexity score (MCS) to identify the
3 degree of modules' complexity. Asikoglu and Simpson (2012) introduced wMCS based on the MCS. The
4 wMCS includes six different types of interface and its weight value. Jung and Simpson (2014) developed two
5 modularity indices to measure the proximity of components to the diagonal of a DSM and to measure
6 modularity independency.
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11 On the literature review on modular design, most of the modularization methods had identified modules to
12 minimize product complexity for manufacturing based on physical or functional interrelationships between
13 components. However, few studies have addressed how to identify the modules to enhance product recovery
14 processes. In order to develop eco-modular architecture, we use current modular product design as the
15 foundation of modularization and extended the design to consider the product recovery. To consider product
16 recovery, modular drivers related to the product recovery are needed to identify the eco-modular architecture.
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18 To measure the modularity of the modular architecture, most of the modularity assessment methods have
19 focused on measuring intra- and inter- connectivity of modular architectures. Modularity assessment in previous
20 research has not considered the product recovery in their product design. The eco-modular product design
21 focuses on the modular architecture by considering how the product will be recovered. Therefore, this new
22 concept of a modularity assessment method is needed to assess the eco-modular architecture based on the
23 modular drivers.
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40 **2.2 Product recovery**

41 Product recovery at the EOL stage is a promising solution to the challenges of achieving sustainable product
42 design and sustainable business. The product recovery is a process of restoring the inherent value of retired
43 products when the products no longer satisfy customers' needs (Lindahl et al. 2006). Reusable components and
44 modules, and recyclable materials are retrieved from the retired products for the product recovery which results
45 in the retrieved modules, components and materials having a second life. The main contribution of the product
46 recovery is to minimize the amount of waste disposal and the usage of natural resources by recovering obsolete
47 parts to serviceable parts. Recovery options include recycling and reuse; additionally, reconditioning,
48 refurbishment, and remanufacturing options are utilized to retrieve products or modules for reuse (Thierry et al.
49 1995).
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2 In order to consider the product recovery in early product design stage, design for disassembly (DfD) was
3 researched to easily and effectively take products apart for reuse and/or recycle in the EOL stage (Lambert
4 2002). DfD mainly focused on disassembly sequence planning by minimizing disassembly cost and time rather
5 than identifying the modules (Behdad et al. 2014; Smith et al. 2012; GÜngÖr and Gupta 2001; Smith and Chen
6 2011). Several studies dealt with product architecture, EOL values and strategies, and the DfD. Kwak et al.
7 (2009) introduced a new concept of eco-architecture to allocate modules with the EOL strategy from the
8 viewpoint of product retirement. Linear programming was used to identify eco-architecture that consists of eco-
9 modules and its EOL strategy based on disassembly cost and an economic value. Behdad et al. (2010) extended
10 the work of Kwak et al. (2009) to consider sharing disassembly operations between products with similar
11 product architecture. Modular architectures were assumed and represented by transition matrix based on a
12 disassembly order. Ishii et al. (1994) suggested a method for evaluating design for product retirement based on
13 modular architecture with quantitative retirement cost analysis and qualitative guidelines. The major factors of
14 the evaluation method were material compatibility and system disassembly cost. Although the method was built
15 based on the modular architecture, module identification was assumed. Tseng et al. (2008) clustered modules
16 based on liaison intensity values that measured assembled connections between components. The grouping
17 genetic algorithm was applied to maximize the liaison intensity within the modules and to minimize the liaison
18 intensity between the modules, as carried out in the conventional modularization method.

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20 As aforementioned, previous research for product recovery has focused on the disassembly planning for
21 minimizing disassembly costs based on predefined modules rather than configuring modules and modular
22 architecture for the product recovery strategy. On the other hand, previous research for modular product design
23 has mainly focused on developing modular product architecture for manufacturing by decomposing a product
24 into modules and components at the system-level design stage of the product development process (Ulrich and
25 Eppinger 2008). Although a product concept has already been determined, alternatives of feasible product
26 architecture can be developed to reflect a product recovery strategy into product architecture design towards a
27 sustainable product at this stage. In this respect, specific design information related to the product recovery
28 strategy from detail design stage, like material types and lifespan of components, is used in this research.
29 Therefore, the proposed methodology can be used at the early product design stage, specifically, the system-
30 level design and detail design stages to develop an eco-modular product architecture. In terms of facilitating the
31 product recovery at the product architecture level, the proposed methodology contributes to design activities for

enhancing the recyclability and reusability of products without further disassembly at material or component levels.

3 An eco-modular architecture design and assessment methodology

The proposed eco-modular architecture design methodology is shown in Figure 1. A design team developing a new product portfolio by considering product recovery would carry out the process outlined here. The process is similar in determining modular product architecture based on the basic physical interrelationships of each product in the product portfolio. However, the design team would include considerations of the product recovery process into its product architecture. We define eco-modular architecture as a scheme by which the components with similar design features are organized into modules to enhance end-of-life characteristics of the architecture. The first step is to analyze current product architecture and product information. Designers can obtain the information on components' interaction based on the DSM, the types and number of interfaces, its complexity, material types, component lifespan, environmental impact and so on from this initial step. In step 2, sustainable modular drivers are identified and measured to cluster components into modules for product recovery. It is important to produce a feasible architecture design, so that physical connections between components are considered to develop eco-modular product architecture. The DSM from step 1 and the values of the sustainable modular drivers from step 2 are converted to an adjacency matrix in step 3. Based on the adjacency matrix, the Markov Cluster Algorithm is applied to identify eco-modular architectures while considering both the physical relationships between components and the sustainable modular drivers. The final step is to assess the modular architectures based on the module independence and similarity metrics. The module independence metric can measure interface complexity between modules to verify how complex the modular product is when disassembling modules at the EOL stage. The module similarity metric assesses the similarity of characteristics of the components in modules of a product. Finally, decision makers can select an eco-module architecture based on the assessment result.

Figure 1 will be inserted here

3.1 Product architecture analysis

Product architecture can be defined as comprehensive representations of a set of characteristics, such as the number and type of components, the number and type of interfaces between components, and the fundamental

1 structure of the product (Fixson 2005). In order to emphasize design for recovery, the product architecture is
2 explained with disassembly process as shown in Figure 2. A product is disassembled into components through
3 modules which are sub-assemblies. The disassembly process incurs different amounts of disassembly process
4 costs according to the difficulty of disassembly and the condition of modules after disassembly (Otto and Wood
5 2001). In the disassembly process of the architecture level, designers can collect information on the negative
6 environmental impact, disassembly cost, product recovery cost, and reassembly cost. The product recovery and
7 reassembly operations are then conducted to retrieve obsolete components. After disassembling the modules
8 into components, the components can then be further disassembled into materials if a module contains
9 components with different materials. The component based DSM is developed to represent interactions between
10 components in a product. The component based DSM is used as a fundamental tool to represent interface
11 complexity in Section 3.2.1 and develop adjacency matrices for the similarities of material or lifespan in Section
12 3.3.

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25 **Figure 2 will be inserted here**

26 27 28 **3.2 Identification of sustainable modular drivers**

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31 Based on the product information, new modular drivers are required to be identified to configure modular
32 architecture for the EOL stage. The modular drivers are used as different criteria to generate modules behind
33 modularization (Erixon 1996). Erixon (1996) introduced 12 modular drivers to satisfy a company's strategic
34 requirements: carryover, technology push, common unit, maintenance and recycling, to name a few.

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37 In this research, sustainable modular drivers related to product architecture and sustainability are introduced
38 to consider disassemblability for the product recovery as shown in Figure 3. An architecture factor is interface
39 complexity; this represents the complexity of functional and geometric connections between components. The
40 interface complexity helps determine modules with high interface complexity between components to minimize
41 interface complexity between the modules. The sustainability factors are component lifespan and materials. The
42 sustainable factors are identified to cluster components with similar material or lifespan to form modules
43 without disassembly at either the component or material levels. These sustainability modular drivers help
44 reconstruct the modular architecture of commercial products into eco-modular architecture.

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47 **Figure 3 will be inserted here**

3.2.1 Interface complexity

As modular product design aims to maximize internal coupling within modules and minimize external coupling between modules (Ulrich 1995), managing the ‘coupling’, which refers to the interface in this research, is important. The interface connects functions through material, energy, and signal flows among components via geometric contacts (Hirtz et al. 2002). Thus, the interface plays a critical role in estimating the difficulty of disassembly as well as the functional importance between components and modules, quantitatively.

In this research, we adopted interface types and weights that were introduced by Asikoglu and Simpson (2012). The interface types related to the physical connection are the attachment (A) and spatial (S), while the interface type related to functional interfaces are transfer (T), control and communication (C), field (F), and power (P) as shown in Table 1. The complexity of direct connections between components/modules is calculated by using the weighted-modular complexity score (wMCS) in equation (1) (Asikoglu and Simpson 2012).

$$\begin{aligned} wMCS = & [w_i \times (\# \text{of } 1's \times 1)] + [w_i \times (\# \text{of } 2's \times 2)] + \\ & [w_i \times (\# \text{of } 3's \times 3)] + [w_i \times (\# \text{of } 4's \times 4)] + \\ & [w_i \times (\# \text{of } 5's \times 5)] + [w_i \times (\# \text{of } 6's \times 6)] \end{aligned} \quad (1)$$

Where, w_i is a weight of an interface type ($i = A, S, T, C, F, \text{ or } P$) as shown in Table 2. The weights (w_i) of different types of interfaces in Table 2 were determined based on the frequency of occurrence of interface types by using a non-linear weight function (Asikoglu and Simpson 2012). There are six levels of complexity according to combinations of interface types. The terms “# of 1’s, 2’s, 3’s, and etc.” are the number of interface complexity at each level, while the numbers 1 to 6 following these terms refer to the complexity constants at each level (Dobberfuhr and Lange 2009). To calculate wMCS, the number of interfaces at each level is multiplied by the weights (w_i) and complexity constant.

Table 1 Definition of interface types (Asikoglu and Simpson 2012)

Interface type	Definition
Attachment (A)	The structural connections between two components that require a type of connector (e.g. bolts, screws, rivets)
Spatial (S)	The geometrical and locational constraints of a component with respect to other components (e.g. snap-fit, welding)
Transfer (T)	The flow of materials or power between components (e.g. water flow in a coffee maker or in an iron)
Control & Communication (C)	The relationship of signal or information flow is communicated or controlled by another component. (e.g. circuit boards)
Field (F)	The interaction between two components in which one component can generate heat, vibration, or magnetic field
Power (P)	The electrical connection between two components unlike communications and controls interfaces

Table 2 Weight value of interface types (Asikoglu and Simpson 2012)

Interface	Weight	Interface	Weight	Interface	Weight	Interface	Weight
A	2.974	SC	21.435	ATC	64.025	PCF	76.142
S	1.795	SF	22.843	ATF	66.137	TCP	75.598
P	6.832	SP	17.253	ATP	57.752	TFP	77.710
C	8.923	TC	36.735	ACF	64.568	ASTC	92.546
T	9.445	TF	38.143	ACP	56.184	ASTF	95.362
F	9.627	PF	32.916	AFP	58.296	ASTP	84.182
AS	9.538	CF	37.098	STC	60.488	ATCF	123.872
AT	24.838	PC	31.508	STF	62.600	ATCP	112.692
AC	23.793	AST	42.642	STP	54.215	ACFP	113.418
AF	25.201	ASC	41.074	SCF	61.032	ASTCF	163.815
AP	19.611	ASF	43.186	SCP	52.647	ASTCP	149.841
ST	22.480	ASP	34.801	SFP	54.759	ASTCFP	237.568

For example, in Figure 4 (a), the number '1' in the cells of the DSM means that there are interconnections between two components. Based on the interconnections of the DSM in Figure 4 (a), the interface complexity is determined in the cells that have the interconnections in Figure 4 (b). For example, when the interface type between components A and C are two screws (Type A) and one snap-fit (Type S), the value of the interface complexity is 7.743 (=2.974 (A)×2 + 1.795 (S) ×1).

Figure 4 will be inserted here

3.2.2 Material

Environmental responsibility of manufacturers is extended beyond the manufacturing stage to customer usage stage and the EOL stage in the product lifecycle. Environmental regulations, such as the WEEE (Waste of Electrical and Electronic Equipment), EuP (Energy Using Product), and ELV (End-of-Life Vehicles), concerns fabrication and disposal of products (Kwak et al. 2009). Carefully selecting materials by considering the customer usage stage and the EOL stage is one of the most important considerations. From the consumer's point of view, certain materials can affect their health; from the manufacturer's perspective, the depletion of natural resources through overconsumption must be considered. Materials are selected in different ways to optimize production methods, function and structural demands, market or user demands, design, price, environmental impact, and lifetime (Ljungberg 2007). To minimize environmental impact, products at the EOL stage should be recycled and reused. Since modular architecture consists of modules that can be disassembled as a chunk, it can inherently improve disassemblability of the products. Accordingly, in terms of design for recycling, components with similar materials should be grouped in a module if components can be recycled by the same product recovery process. This will be advantageous in terms of reducing disassembly costs and recycling processes.

3.2.3 Lifespan

Lifespan is related to the residual value of an EOL product which is changing over time. When a product or a module is disposed of because of physical deterioration or technology obsolescence, the residual value is an indicator of whether or not the module can be performed for a second life. Therefore, the residual value of a product was estimated by its physical and functional lifetimes based on the empirical disposal data of the product in the market. The remaining lifetime (L_R) for the product recovery is represented with its mean lifetime (L_M) and actual lifetime (L_A) under the operation conditions as shown in equation (2) (Mazhar et al. 2007).

$$L_R = L_M - L_A \quad (2)$$

L_M is the component's total functional life and is estimated by the time-to-failure data for a family of components, while L_A depends on the actual used condition. The L_M of each component can be obtained by the empirical time-to-failure data and estimated by Weibull analysis (Kara et al. 2005). The cumulative distribution function for the Weibull distribution is:

$$F(t; \beta, \eta) = 1 - \exp \left[- \left(\frac{t}{\eta} \right)^\beta \right] \quad (3)$$

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Where, t is time to failure. The distribution is affected by two parameters: the scale parameter, η , and the shape parameter, β . The value of β is closely related to failure mode. When $\beta < 1$, there is infant mortality. $\beta = 1$ means that the failure rate is constant over the time (random failure). $\beta > 1$ indicates a high failure rate as time passes. The mean life L_M is measured by using the following equation (Mazhar et al. 2007):

$$L_M = \eta \Gamma \left[\frac{\beta + 1}{\beta} \right] \quad (4)$$

In product recovery, the product lifespan can be an attribute for modular design. With a modular design method, components with similar or high lifespan can be grouped into a module. The components in the module can be treated by the same or similar reuse processes, so that a company can save recovery process costs.

3.3 Identifying eco-modules based on Markov Cluster Algorithm

After measuring and/or collecting the value of the sustainable modular drivers, the value is represented as an adjacency matrix to cluster components with similar material or lifespan into modules. Based on the adjacency matrix as an input, the eco-modular product architectures are configured by Markov Cluster Algorithm (MCL).

The MCL was developed by Van Dongen (2000) and is a commonly used algorithm for clustering networks in the field of bioinformatics (Lei et al. 2016). As this algorithm is simple, there is no high-level procedural instruction for assembling, joining, or splitting of groups (Van Dongen 2000). The MCL can generate modules with high similarity values, and dismiss the connections between components that have low similarity based on the sustainable modular drivers. In this respect, we used the MCL to generate eco-modular architectures.

The clustering process by the MCL is explained in Figure 5. Intuition of graph clustering is to group nodes connected with high strength in one cluster. The MCL finds clusters in graphs by a mathematical bootstrapping procedure. The procedure is to compute random walks through the graph by using stochastic matrix (also called Markov matrix) that represents the mathematical concept of the random walks on the graph (<http://micans.org/mcl/>). The random walks in the MCL algorithm infrequently transit from node i in one cluster to another cluster to lead to node j in the same cluster (Bernardes et al. 2015). The MCL is a fast and scalable unsupervised clustering algorithm based on simulation of stochastic flow in a graph.

Figure 5 will be inserted here

In the MCL, an adjacent matrix is developed with values of the sustainable modular drivers as weight value on the edges. The edges are identified by the physical relationships in the component based on the DSM. Then,

the adjacent matrix is converted to a weighted undirected graph. Let $G=(V,E)$ be the undirected graph that includes self-loops; V denotes the node set and E means the edge set. A node in V is v_i , and an edge between v_i and v_j in E is represented as (v_i, v_j) . A weight value on the edge is denoted as $w(v_i, v_j)$, which represents the interface complexity, material similarity, or lifespan similarity. A is the adjacency matrix of a weighted and undirected graph as follows:

$$A(i, j) = \begin{cases} w(v_i, v_j) & \text{if } (v_i, v_j) \in E \\ 0 & \text{else} \end{cases} \quad (5)$$

When developing the adjacency matrix for material similarity, the material similarity is decided according to the experts' knowledge based on the material information, such as material property, conditioning process, recovery process, and so on. In this research, to simplify calculating the material similarity, the weight value of the material similarity is represented between 0 and 1. Equation (6) is an example of the weight value.

$$w(v_i, v_j) = \begin{cases} 1 & \text{if same material is used in } i\text{th and } j\text{th components} \\ 0.5 & \text{if similar materials are used} \\ 0.3 & \text{else} \end{cases} \quad (6)$$

For measurement of lifespan similarity between two components, the lifespan of components has to be predicted by designers based on the accumulated company data and knowledge. Then, the lifespan similarity between components is decided to build an adjacency matrix. Calculation of the lifespan similarity is represented by a ratio of the minimum lifespan and maximum lifespan between v_i and v_j in equation (7). If the lifespan is the same, the lifespan similarity would be 1. On the other hand, the lifespan similarity value would be close to 0. This means that one of the components has a short lifespan or there is a big difference in lifespans.

$$w(v_i, v_j) = \frac{\min \text{ lifespan}(v_i, v_j)}{\max \text{ lifespan}(v_i, v_j)} \quad (7)$$

When considering these modular drivers together, the weighted value of edges (\bar{W}) is calculated by the weighted average method as illustrated in equation (8).

$$\bar{W}(i, j) = \frac{w_1 \times \text{Interface complexity}(i, j) + w_2 \times \text{Material similarity}(i, j) + w_3 \times \text{Lifespan similarity}(i, j)}{w_1 + w_2 + w_3} \quad (8)$$

$$\sum_{i=1}^3 w_i = 1$$

Where, w_i is the weighted value of each sustainable modular driver.

After building the adjacent matrix, the adjacency matrix $A(i,j)$ should be transformed to Markov matrix, M , that is diagonally similar to a symmetric matrix. In order to identify random walks from the adjacency matrix, the sum of all outgoing edges, which is the sum of each column, equals to one as shown in equation (9). So, $M(i,j)$ represents the probability of transition of the random walks, which is termed as stochastic flow, from v_i to v_j (Van Dongen 2000).

$$M(i, j) = \frac{A(i, j)}{\sum_{k=1}^n A(k, j)} \quad (9)$$

The MCL process contains two operations: *expansion* and *inflation*. The expansion operation is normal matrix multiplication and represented as $M_{exp} = M \times M$. It allows the flow to connect different regions of the graph and becomes more homogenous. The expansion corresponds to random walks with many steps. It associates new probabilities with all pairs of nodes, where one node is the point of departure and the other is the destination. Higher length paths are more common within a cluster than between clusters.

$$M_{inf}(i, j) = \frac{M(i, j)^r}{\sum_{k=1}^n M(k, j)^r} \quad (10)$$

The inflation models the contraction of the flow in equation (10). It becomes thicker in regions of higher value on edges and thinner in regions of lower value on edges. The inflation operation has the effect to rescale each of the columns of M with the inflation parameter r . The parameter r is a non-negative real number. Each column j of a Markov matrix M is node j of the stochastic graph G . The inflation operation results in the stochastic matrix M_{inf} . The elements of the matrix M_{inf} correspond to the probability values on the edges. The inflation will boost the probabilities of intra-cluster and dismiss the probabilities of inter-cluster to result in cluster structures. Iterating expansion and inflation result in different clusters of the graph. Therefore, eco-modular architectures are generated based on adjacency matrix from each modular driver.

3.4 Assessment of modular architectures

After determining the eco-modular architectures, an assessment should be made of whether the architectures reflect the intent of the sustainable modular drivers or not. Since modular product architecture is composed of interfaces and modules, we propose two modularity metrics to assess interfaces and modules: (1) module independence (MI) to assess interface complexity between modules; and (2) module similarity (MS) to analyse similarity within modules as shown in Figure 6. The MI is a ratio of interface complexity between modules to

total interface complexity of a product in equation (11). The module similarity metric is the degree of similarity within modules in product architecture as shown in equation (12).

The following are assumptions to assess modular architectures with EOL strategies. (1) It is assumed that the MI metric represents the difficulty of disassembly. (2) It is assumed that the MS metric represents possibility of disassembly. This is because a module requires further disassembly at component or material level during product recovery process if modules have components with less similarity of lifespan or material. (3) It is assumed that the lifespan of a component is estimated by the Weibull analysis based on accumulated company data, and the lifespan of the component which is longer than a product lifespan can be performed well for its remaining life.

Figure 6 will be inserted here

MI has been modified from Newcomb et al. (1998). The MI can be calculated by a ratio of intra-module interface complexity for all modules and total interface complexity in equation (11).

$$\text{Module independence (MI)} = \frac{\sum_{i=1}^N \text{Intra-module interface complexity}_i}{\text{Total interface complexity}} \quad (11)$$

The MI is calculated by using intra-module interface complexity instead of inter-module interface complexity because it yields that the MI is a maximum value when the interface complexity is low. Theoretically, the maximum value of MI is 1 if all connections are within modules but there are no connections between modules in a product. The minimum value of MI is 0 when the modules are a single component.

Since eco-modular product architectures were identified based on similar values, a designer has to assess the degree of similarity in each module. The MS is assessed by following equation (12).

$$\text{Module similarity (MS)} = \frac{\sum_{i=1}^N \text{Max}(S_{i,j})}{N} \quad (12)$$

$$S_{i,j} = \left[\frac{S_{i,1}}{n}, \frac{S_{i,2}}{n}, \dots, \frac{S_{i,j}}{n} \right], \quad \sum_{j=1}^n S_{i,j} = n \quad (13)$$

Where $S_{i,j}$ is the similarity ratio of j th different characteristics to the number of components in i th module (n), N is the number of modules in a product. For example, the first module consists of a component with a lifespan of 5 years ($s_{1,1}$), three components with a lifespan of 8 years ($s_{1,2}$), and two components with a lifespan of 10 years ($s_{1,3}$). In this case, the number of components in the first module is 6 ($n=6$), and $S_{1,j}=[1/6, 3/6, 2/6]$. As $S_{1,2}$ equals 0.5 which is the maximum value of the first module, it represents a lifespan similarity (S_l) of the first module based on equation (12) and (13). However, $S_{i,j}=0$ when all components have different lifespans. If all modules in a product consist of components with the same materials, $MS = 1$. Otherwise, it is 0 if each module has components with all different materials. Finally, to consider the MI and MS simultaneously, the modularity for the EOL stage (M_{EOL}) is developed by using the weighted average calculation as shown in equation (14). The modularity ranges from 0 to 1.

$$\text{Modularity for EOL stage } (M_{EOL}) = w_1 MI + w_2 MS_{Material} + w_3 MS_{Lifespan} \quad (14)$$

$$\sum_{i=1}^3 w_i = 1 \quad (15)$$

When M_{EOL} is close to 1, the modular architectures can be designed well with considerations of the product recovery. Accordingly, designers can choose an eco-modular architecture of which M_{EOL} is close to 1. As the M_{EOL} measures the modularity only for the EOL stage and is flexible, the M_{EOL} can be modified by adding other similarities that designers wish to measure. Figure 7 shows the proposed four regions with two thresholds (θ_1, θ_2) that indicate decision points for determining categories of a product architecture for EOL recovery options. The value of the thresholds can be decided by design strategies including customer demands for recovered products/modules, recovery cost and profit, and quality of recovered products/modules. The categorized architectures (g) can be represented as equation (16) based on the MI and MS, and provide a guideline for eco-modular architectures in the viewpoint of disassembly for product recovery.

$$g = \begin{cases} A, & \text{if } MS \geq \theta_1, MI \geq \theta_2 \\ B, & \text{if } MS \geq \theta_1, MI < \theta_2 \\ C, & \text{if } MS < \theta_1, MI \geq \theta_2 \\ D, & \text{if } MS < \theta_1, MI < \theta_2 \end{cases} \quad (16)$$

The four regions of product architecture are proposed based on the MI ($0 \leq MI \leq 1$) and the MS ($0 \leq MS \leq 1$): (A) eco-modular architecture, (B) eco-modules with high disassembly cost and time, (C) component reuse or recycle, and (D) disposal of a product as shown in Figure 7 (a). The eco-modular architecture in region A provides efficiency for product recovery process by minimizing the possibility of disassembly operations, and disassembly cost and time. In region B, the eco-modular architecture with high disassembly cost and time

provides eco-modules but these connect with high interface complexity. These two eco-modular architectures can be processed for product recovery at the sub-assembly level in Figure 7 (b). However, when the module similarities are low because modules contain components with different lifespans and materials as shown in region C, the modules have to be disassembled into components or materials. Then, components can be recycled or reused if interface complexity between modules is low. In region D, as both the module similarity and independence are low, the product can be disposed of.

Figure 7 will be inserted here

To demonstrate the effectiveness of the proposed eco-modular design and assessment methodology, a case study is performed with a coffee maker in the next section.

4 Case study

In this section, the proposed design methodology is described with a case study of a coffee maker. The electric coffee maker is composed of a simple structure and mechanism but is still efficient. The specification of the coffee maker is described in Table 3. A functional diagram of the coffee maker is shown in Figure 8. The functional diagram represented energy, material, and signal flows between components (Hirtz et al. 2002).

Table 3 Specification of the coffee maker

#	Part name	Material	Weight(g)	Model (Philips HD7450)
1	Bottom cover	PP	80.5	 <p>220V, 50Hz, 650W 4~6 cups / 0.6 L Brewing time < 10 minutes</p>
2	Silicon ring	Silicon	1.8	
3	Hot plate	Al	61.3	
4	Casing for heater	PP	55.2	
5	Heater	Al	118.2	
6	Power cord	Copper	120	
7	Water tube set	PP	14.7	
8	Silicon tube	Silicon	21.4	
9	Water reservoir	PP	243.2	
10	Steam sprout	PP	11.5	
11	Filter basket	PP	79.1	
12	Filter	PP	12.0	
13	Lid of coffee maker	PP	72.6	
14	Decanter	Glass	214.5	
15	Bottom casing	PP	155.0	

Figure 8 will be inserted here

4.1 Product architecture analysis

The physical relationships between components were identified after decomposing the coffee maker. The DSM was applied to represent interrelationships among components as shown in Figure 9. Accordingly, the DSM was used to develop an interface and adjacency matrix shown in Section 4.2. Modules were generated by the DSM clustering algorithm by Thebeau (2001). As shown in Figure 9 and the first column of Table 9, there are five modules: 1) bottom casing; 2) decanter and connecting parts; 3) water reservoir (upper casing) and water tube parts; 4) filter; and 5) heater.

Figure 9 will be inserted here

4.2 Identification of modular drivers for sustainable design

Interface design of the coffee maker was assessed based on equation (1) and the number of interface types and its weight values based on Table 2. As shown in Table 4, direct relationships between any two components were represented by the definition of the interface type. For example, Heater (No.5) and Silicon tube (No.8) are spatially connected from Water reservoir to Heater, and from the Heater to the Steam sprout. So, 'S(2)' means that there are two spatial contacts. As the Heater and the Silicon tube transfer water in the coffee maker, it is also a 'Transfer (T)' interface type. The complexity of interface was developed as the adjacency matrix in Table 5.

Table 4 Interface matrix with interface types

	Interface	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
1	Bottom cover				S											A(3),S
2	Silicon ring			S	S											
3	Hot plate		S		S	S,F									S,T	S
4	Casing for heater	S	S	S	S	S										S
5	Heater			S,F	S		P		S(2),T						F	S
6	Power cord					P										S
7	Water tube set								S(2),T(2)							
8	Silicon tube					S(2),T		S(2),T(2)		S,T	S,T					
9	Water reservoir								S,T	S(2)	S			S		A(3),S
10	Steam sprout								S,T	S(2)	T			S(2)		
11	Filter basket									S	T		S,T		S,T	
12	Filter										S,T					
13	Lid of coffee maker									S	S(2)					S(2)
14	Decanter			S,T		F						S,T				S
15	Bottom casing	A(3),S		S	S	S	S				A(3),S			S(2)	S	

Table 5 Adjacency matrix with interface values

	Interface	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
1	Bottom cover				1.795											10.717
2	Silicon ring			1.795	1.795											
3	Hot plate		1.795		1.795	11.422									11.240	1.795
4	Casing for heater	1.795	1.795	1.795		1.795										1.795
5	Heater			11.422	1.795		6.832		13.035						9.627	1.795
6	Power cord					6.832										1.795
7	Water tube set								22.480							
8	Silicon tube					13.035		22.480		11.240	11.240					
9	Water reservoir								11.240		3.590	1.795		1.795		10.717
10	Steam sprout								11.240	3.590		9.445		3.590		
11	Filter basket									1.795	9.445		11.240		11.240	
12	Filter											11.240				
13	Lid of coffee maker									1.795	3.590					3.590
14	Decanter			11.240		9.627						11.240				1.795
15	Bottom casing	10.717		1.795	1.795	1.795	1.795			10.717				3.590	1.795	

To build the adjacency matrix for the clustering of modules, the information of each component was analysed as shown in Table 6. The typical lifespan of the drip filter coffee machine was approximately 6 years and was approved by the European Committee of Domestic Equipment Manufacturers and other stakeholders (European Commission 2011). In the case of the product lifespan of components, as the coffee maker has a simple function and operating conditions, the lifespan of components would then only largely be affected by material types. Accordingly, we assumed an average lifespan of each component based on material types. The lifespan of components made of aluminum, copper, and glass was assumed as 10 years, and the lifespan of components made of PP or silicon was assumed as 8 or 5 years, respectively in Table 6.

Table 6 Material types and estimated lifespan of the coffee maker

#	Part name	Material	Typical product lifespan	Estimated component lifespan
1	Bottom cover	PP	6	8
2	Silicon ring	Silicon		5
3	Hot plate	Al		10
4	Casing for heater	PP		8
5	Heater	Al		10
6	Power cord	Copper		10
7	Water tube set	PP		8
8	Silicon tube	Silicon		5
9	Water reservoir	PP		8
10	Steam sprout	PP		8
11	Filter basket	PP		8
12	Filter	PP		8
13	Lid of coffee maker	PP		8
14	Decanter	Glass		10
15	Bottom casing	PP		8

Based on the product information, similarities of components were measured by equations (6) and (7). Similarity matrices which are the same as adjacency matrices were developed to represent material similarity and lifespan similarity as shown in Table 7.

Table 7 Adjacency matrix for similarities of (a) material and (b) lifespan

(a)

Material similarity		1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
1	Bottom cover				1.00											1.00
2	Silicon ring			0.30	0.50											
3	Hot plate		0.30		0.30	1.00									0.30	0.30
4	Casing for heater	1.00	0.50	0.30		0.30										1.00
5	Heater			1.00	0.30		0.50		0.30						0.30	0.30
6	Power cord					0.50										0.30
7	Water tube set								0.50							
8	Silicon tube					0.30		0.50		0.50	0.50					
9	Water reservoir							0.50		1.00	1.00	1.00		1.00		1.00
10	Steam sprout							0.50	1.00			1.00		1.00		
11	Filter basket								1.00	1.00			1.00		0.30	
12	Filter											1.00				
13	Lid of coffee maker								1.00	1.00						1.00
14	Decanter			0.30		0.30						0.30				0.30
15	Bottom casing	1.00		0.30	1.00	0.30	0.30			1.00				1.00	0.30	

(b)

Lifespan similarity		1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
1	Bottom cover				1.00											1.00
2	Silicon ring			0.50	0.63											
3	Hot plate		0.50		0.80	1.00									1.00	0.80
4	Casing for heater	1.00	0.63	0.80		0.80										1.00
5	Heater			1.00	0.80		1.00		0.50						1.00	0.80
6	Power cord					1.00										0.80
7	Water tube set								0.63							
8	Silicon tube					0.50		0.63		0.63	0.63					
9	Water reservoir							0.63	0.63	1.00	1.00		1.00			1.00
10	Steam sprout							0.63	1.00			1.00		1.00		
11	Filter basket								1.00	1.00			1.00		0.80	
12	Filter											1.00				
13	Lid of coffee maker								1.00	1.00						1.00
14	Decanter			1.00		1.00						0.80				0.80
15	Bottom casing	1.00		0.80	1.00	0.80	0.80			1.00				1.00	0.80	

4.3 Identifying modules based on the Markov Cluster Algorithm

Based on adjacency matrices, the Markov matrix (M) was determined by equation (9) as shown in Table 8. Eco-modules were determined by using Markov Cluster Algorithm (MCL). Since the proposed methodology arranged constituents in modules while keeping the physical relationships, it could result in feasible eco-module architectures. In the case of the optimal number of modules, we assumed that the number of modules for the coffee maker was decided as five modules to compare alternatives of eco-modular architectures. Accordingly, alternatives of eco-modular architectures were identified based on physical relationship, interface complexity, material similarity, lifespan similarity, and weighted average of these three modular drivers by using MCL as shown in Table 9. The module number in Table 9 did not mean that the same number of modules for each architecture had the same characteristics, but showed that each architecture had five modules.

Table 9 Clustering results based on MCL

Module No.	DSM clustering	MCL				
	Architecture (A) (based on physical relationship)	Architecture (B) (based on physical relationship)	Architecture (C) (based on interface complexity)	Architecture (D) (based on material similarity)	Architecture (E) (based on lifespan similarity)	Architecture (F) (based on weighted average)
1	1	1	1	1	1	1
	4	2	4	2	2	2
	15	3	13	4	3	4
		4	15	15	4	13
		6			6	15
2		14			15	
	2	5	2	3	5	3
	3		3	5	14	5
	14		5	6		6
			6	14		14
3	7	7	7	7	7	7
	8	8	8	8	8	8
	9		9			
	10		10			
4	13					
	11	11	11	11	11	11
5	12	12	12	12	12	12
	5	9	14	9	9	9
	6	10		10	10	10
		13		13	13	

4.4 Assessment of modular architecture

The modularity for the EOL stage (M_{EOL}) was applied to assess each module and architecture. Additionally, the architecture (A) developed by DSM clustering algorithm in Table 9 was also assessed to determine the degree of modularity for product recovery.

From the results of the module independence assessment, architectures (A) and (D) had the highest value with 0.54, while architecture (E) had the lowest value with 0.41 as shown in Table 10. This means that architectures (A) and (D) contain low interface complexity between the modules. From the results of the material similarity assessment, architecture (C) in Table 10 had the highest similarity with 0.85 because all modules contained components with a similar or the same materials, except for the second module. In architecture (C) in Table 9, the second module inevitably contained components with different materials, such as the hot plate (3), heater (5), power cord (6), and decanter (14), to meet the functionality of the product. For results of the lifespan similarity assessment, architecture (C) was also the best architecture with the highest lifespan similarity value, 0.9; this was because almost all the modules contained components with a similar or same lifespan.

Table 10 Modularity assessment results

	MI	MS_material	MS_lifespan	M _{EOL}	MDL
Architecture A	0.54	0.56	0.89	0.66	13.56
Architecture B	0.43	0.69	0.69	0.60	25.12
Architecture C	0.53	0.85	0.90	0.76	24.45
Architecture D	0.54	0.65	0.75	0.64	21.78
Architecture E	0.41	0.50	0.70	0.54	23.12
Architecture F	0.53	0.66	0.76	0.65	24.45

Based on the individual results from the module independence, material similarity, and lifespan similarity, we represented the results on a scatter plot of categorized modular architectures in Figure 10. Two thresholds could be decided to identify four regions of the architectures according to design strategies of a company including customer demands for recovered products, recovery profit, and so on. In this case study, the two thresholds were assumed as $(\theta_1, \theta_2) = (0.7, 0.5)$. Region A contained architectures (A), (C), (D), and (F) with lifespan similarity. However, as the material similarity of these architectures was lower than θ_1 , except for architecture (C), these architectures had to be disassembled at the component level for recycling. Therefore, in this case study, architecture (C) would be the best architecture due to high module similarities within modules and high module independence between modules shown in Figure 10. Also, the M_{EOL} showed that architecture (C) was the best eco-modular architecture with the highest M_{EOL} value in Table 10. For architectures (B) and (E), the designer can plan to dispose of products because product recovery cost and time will be high. The proposed methodology was developed based on physical interrelationships in a product and resulted in the eco-modular architecture illustrated in the functional diagram of architecture (C) in Figure 11. Accordingly, architecture (C) will maintain its functions and enhance the product recovery process. Architecture (C) of this coffee maker could be recycled and reused without further disassembling the modules into components or materials. The characteristics of modules 1, 4, and 5 in architecture (C) could lead to reuse and recycle options because the modules consisted of components with the same material and lifespan. However, as modules 2 and 3 contained components with different materials and lifespans, these modules would have to be disassembled at the component or material levels for product recovery.

Figure 10 will be inserted here

Figure 11 will be inserted here

1 In order to compare a conventional method to the proposed assessment method, we used the minimum
2 description length (MDL) to measure modularity by calculating the coupling complexity of the coffee maker
3
4 (Chiriac et al. 2011) as follows:
5

$$6 \quad MDL = \frac{1}{3} \left(n_c \log_2 n_n + \log_2 n_n \sum_{i=1}^{n_c} cl_i \right) + \frac{1}{3} S_1 + \frac{1}{3} S_2 \quad (17)$$

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8
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10 where, n_c is the number of modules; n_n is the number of components in DSM; and cl_i is the number of
11 components in module i . S_1 is the number of empty cells in a module, while S_2 is the number of cells that have a
12 link between modules. The lower the MDL, the better the modularity of a product. When calculating the MDL,
13 values from the proposed modular drivers were not considered, but the number and size of modules and
14 components were considered. By using the theoretic information, we could identify well-established modules
15 according to the ideal modularity concept that had high internal couplings within modules and low external
16 couplings between modules. In terms of the result from the MDL calculation in Table 10, architecture (A)'s
17 modularity was the best architecture. This was because architecture (A) had less empty cells within modules
18 than other architectures. From the results of Table 10, we could see that different viewpoints of modularity
19 assessments resulted in different priorities of the architectures. With regard to the ideal modularity concept,
20 architecture (A) had the best modules, while architecture (C) had good modularity for the EOL stage. It was
21 difficult to compare the MDL and M_{EOL} because of the different purposes of the modularity. However, the M_{EOL}
22 would be a good starting point to assess modularity for sustainable product design.
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37 Additionally, after deciding the eco-modular product architecture, design improvement in a module level
38 would be needed to produce various product variants including environmentally-friendly products. So, lifecycle
39 assessment was applied to measure the environmental impact of the modules and to redesign the modules
40 regarding material usage. Eco-Indicator 99 was used as the lifecycle assessment tool (Baayen 2000). The Eco-
41 Indicator 99 can measure three types of damage: 1) human health; 2) ecosystem quality (e.g. acidification); and
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48 3) resources.
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Table 11 Environmental impact changes after material reduction

Module No.	Part No.	Part name	Material	Weight (g)	EI (mPt)	Weight change (g)	EI change (mPt)
1	1	Bottom cover	PP	80.5	11.350	-10	-1.41
	4	Casing for heater	PP	55.2	7.783	0	0
	13	Lid of coffee maker	PP	72.6	10.237	0	0
	15	Bottom casing	PP	155.0	21.855	-25	-3.53
2	2	Silicon ring	Silicon	1.8	0.178	0	0
	3	Hot plate	Al	61.3	6.183	0	0
	5	Heater	Al	118.2	11.922	-18.2	-2.40
	6	Power cord	Copper	120.0	168.240	0	0
3	7	Water tube set	PP	14.7	2.073	0	0
	8	Silicon tube	Silicon	21.4	2.119	0	0
	9	Water reservoir	PP	243.2	34.291	-43.2	-6.09
4	10	Steam sprout	PP	11.5	1.621	0	0
	11	Filter basket	PP	79.1	11.153	0	0
5	12	Filter	PP	12.0	1.692	0	0
	14	Decanter	Glass	214.5	6.435	-14.5	-0.44
Sum				1261	294.08	-100.9	-13.87

A scenario was assumed to enhance the product design to include product recovery. For the product recovery, material selection plays a key role in eco-product design because the materials not only can affect the health of consumers but also affect the depletion of natural resources through overconsumption. The material selection relies on expert knowledge in terms of material property, manufacturing process, and safety for users. In this case study, as almost all materials in the coffee maker were recyclable, we assumed that the bottom cover and bottom casing, heater, water reservoir, and decanter were redesigned to reduce material usage by minimizing their size and thickness. Accordingly, the weight was reduced as shown in Table 11. As the result, the weight changes of the materials decreased the environmental impacts after re-design.

5 Closing remarks and future work

In this research, we introduced a methodology to determine the eco-modular product architecture and its modularity assessment for product recovery processes. The proposed methodology contributes to facilitating the product recovery processes by recycling, reusing, and disposing modules without further disassembly at the component or material levels. Also, the methodology helps designers quantify the degree of modularity of the eco-modular architecture from the viewpoint of the end-of-life stage.

In this research, modular product design was extended to consider the product recovery processes which aim to restore the inherent value of retired products. Three sustainable modular drivers were proposed to consolidate components with high similarity and interface complexity into modules, aiming to recover the modules without further disassembly at component or material levels. Markov Cluster Algorithm was applied to identify alternative eco-modular architectures based on these the sustainable modular drivers. To check whether or not

1 the eco-modular architectures reflect the intent of the sustainable modular drivers, a novel methodology has
2 been developed to assess the degree of modularity from the viewpoint of product recovery. The degree of
3 modularity supported the selection of the eco-modular architecture based on the module independence metric
4 between modules and the module similarity metric. To demonstrate the usefulness of the proposed methodology,
5 we performed a case study of a coffee maker.
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10 The limitation of this proposed methodology is that it considers modular architecture for only a single
11 product. More case studies need to be performed with different products to show the scalability and applicability
12 of the proposed methodology. Also, the methodology will be extended to product family architecture design to
13 improve the reusability of the eco-modules by sharing and exchanging the eco-modules in a product family.
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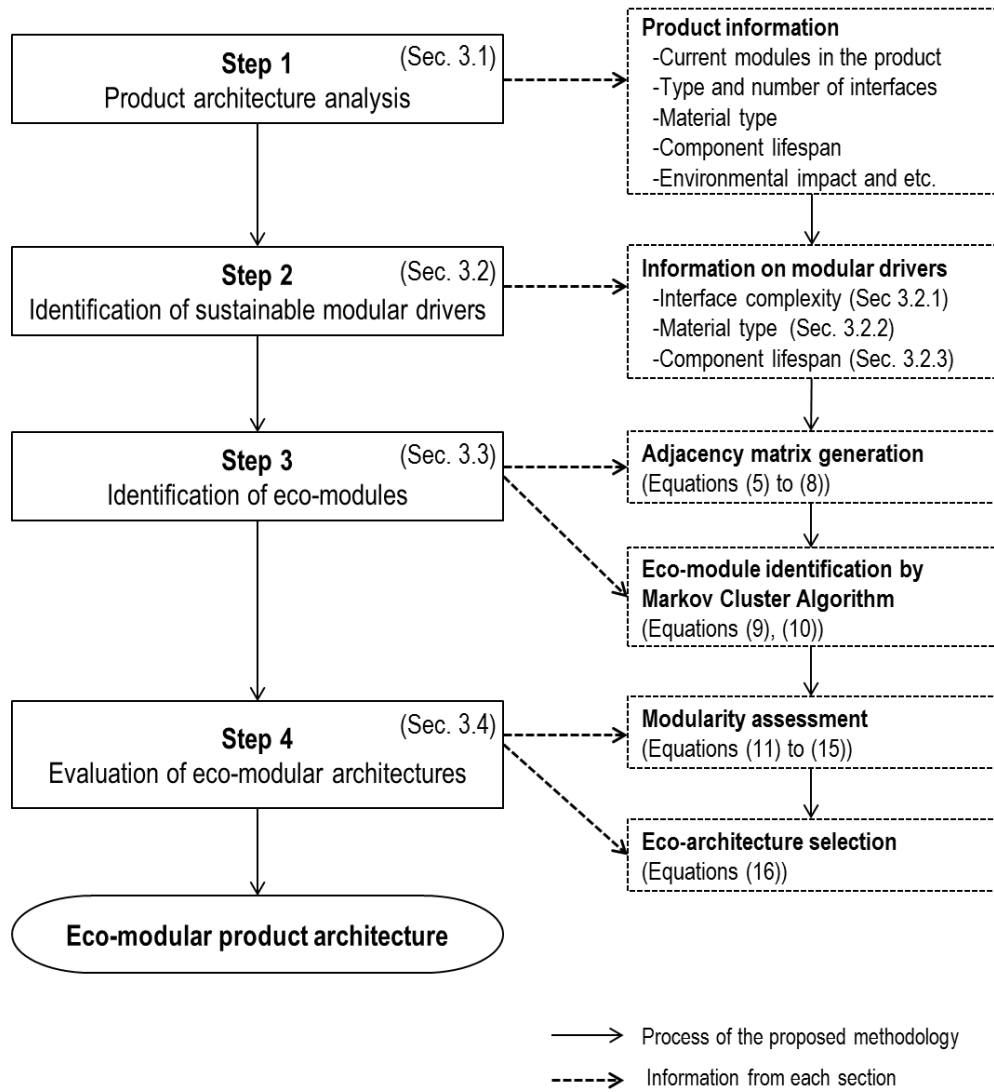


Figure 1 The proposed process for eco-modular architecture design

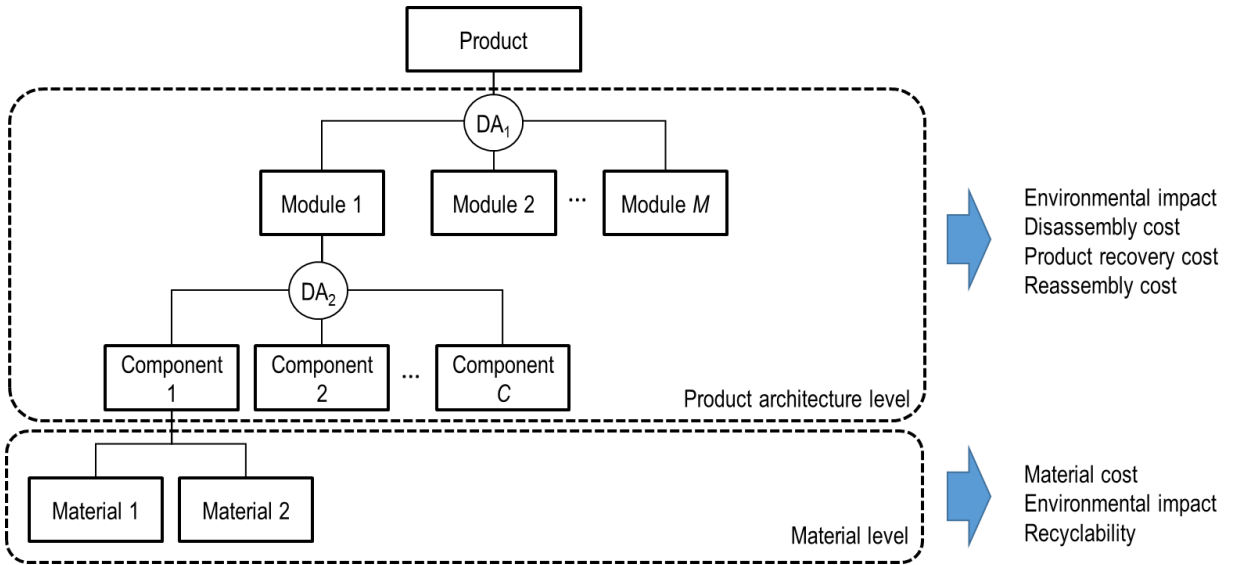


Figure 2 An example of product architecture

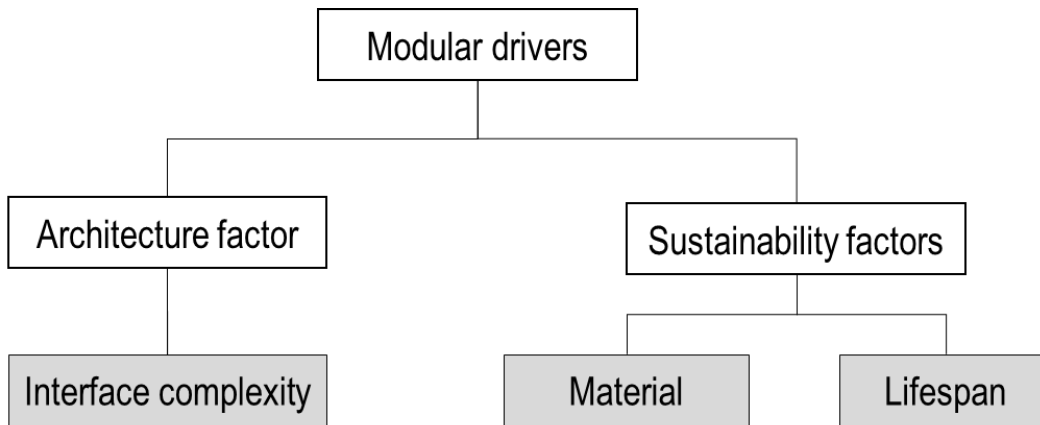


Figure 3 Three sustainable modular drivers

	A	B	C	D	E
A		1	1		
B	1		1		
C	1	1		1	
D			1		1
E				1	

(a)

	A	B	C	D	E
A		A	A(2),S		
B	A		AS		
C	A(2),S	AS		S	
D			S		A
E				A	

	A	B	C	D	E
A		2.974	7.743		
B	2.974		9.538		
C	7.743	9.538		1.795	
D			1.795		2.974
E				2.974	

(b)

Figure 4 An example of DSM with (a) physical relationship and (b) wMCS

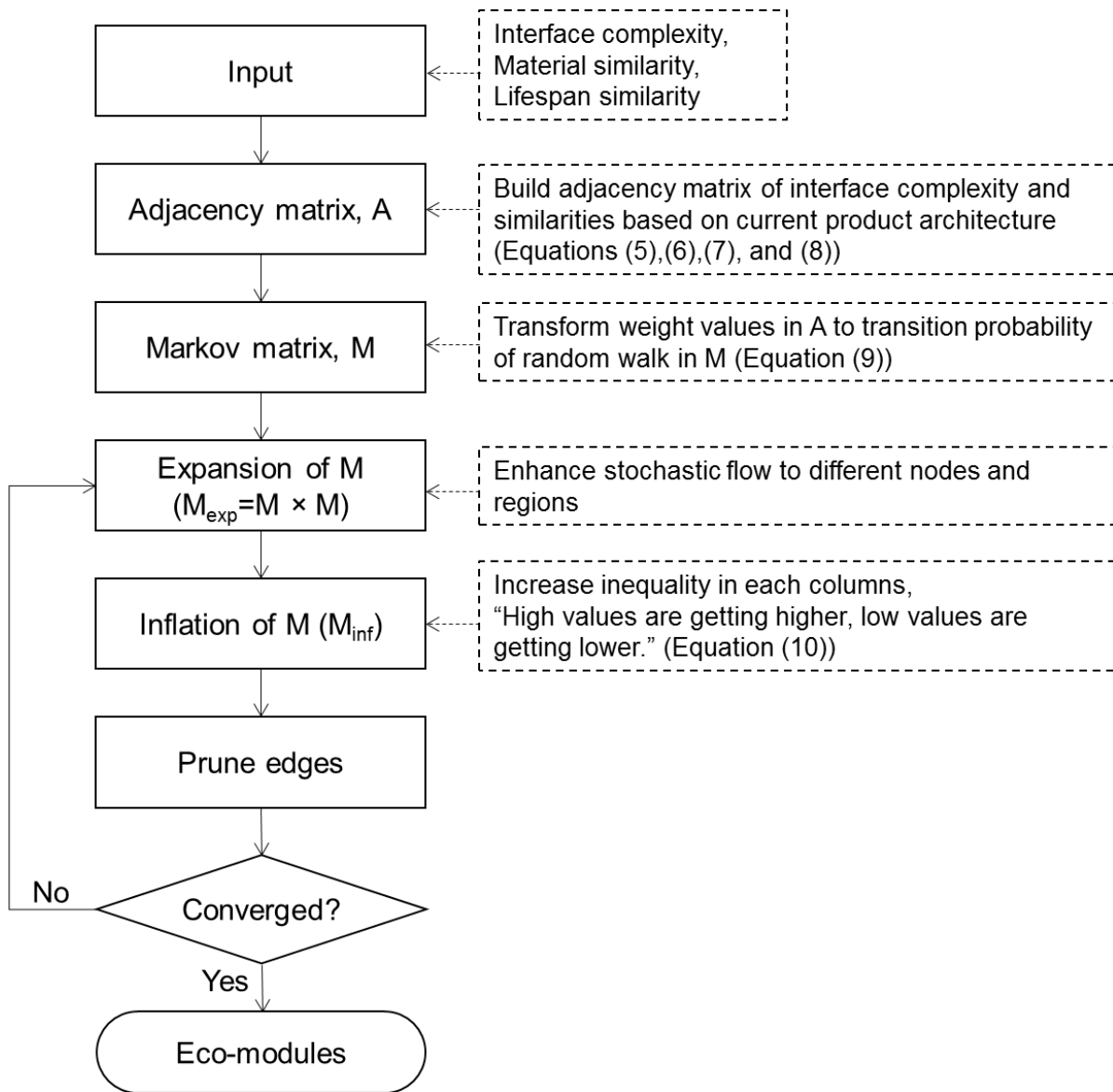


Figure 5 Clustering process for identifying the eco-modules by the MCL

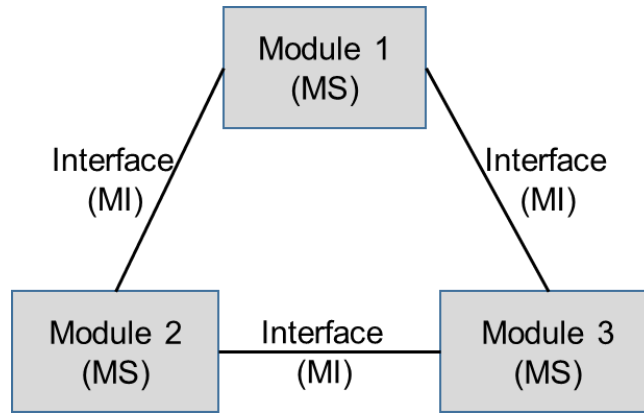
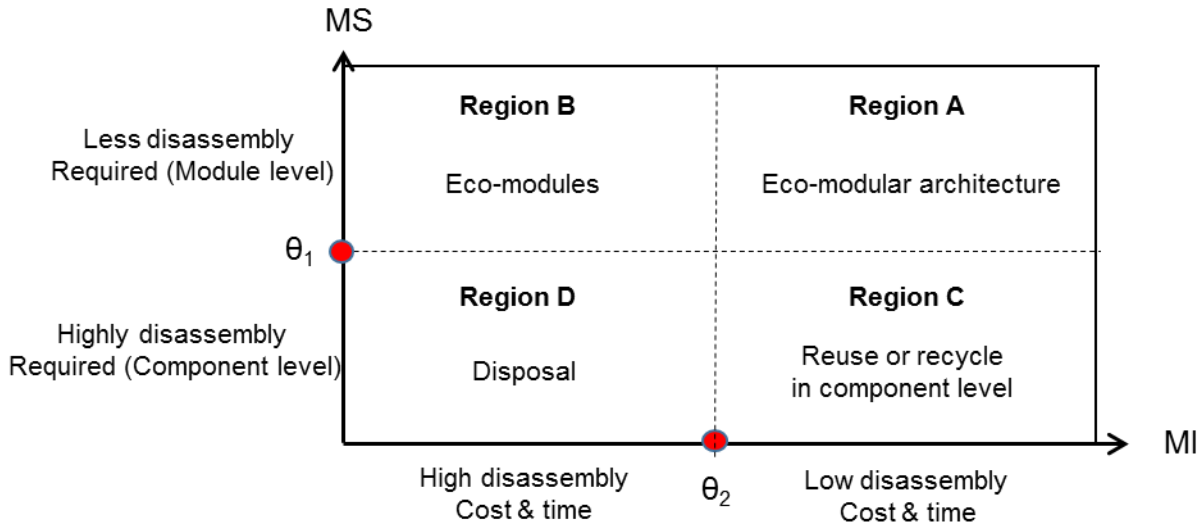
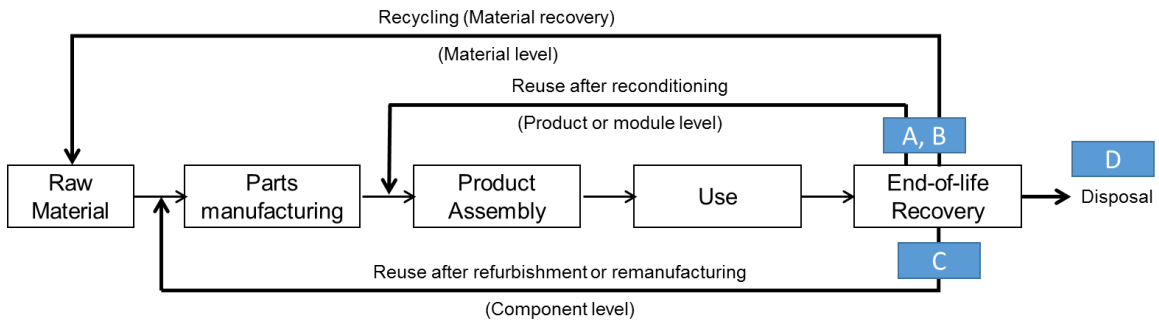


Figure 6 The assessment range of the proposed modularity metrics



(a) Four regions of modular product architecture



(b) Product recovery options of the modular product architecture in the four regions in product lifecycle

Figure 7 Modular architecture categories and their product recovery options in product lifecycle

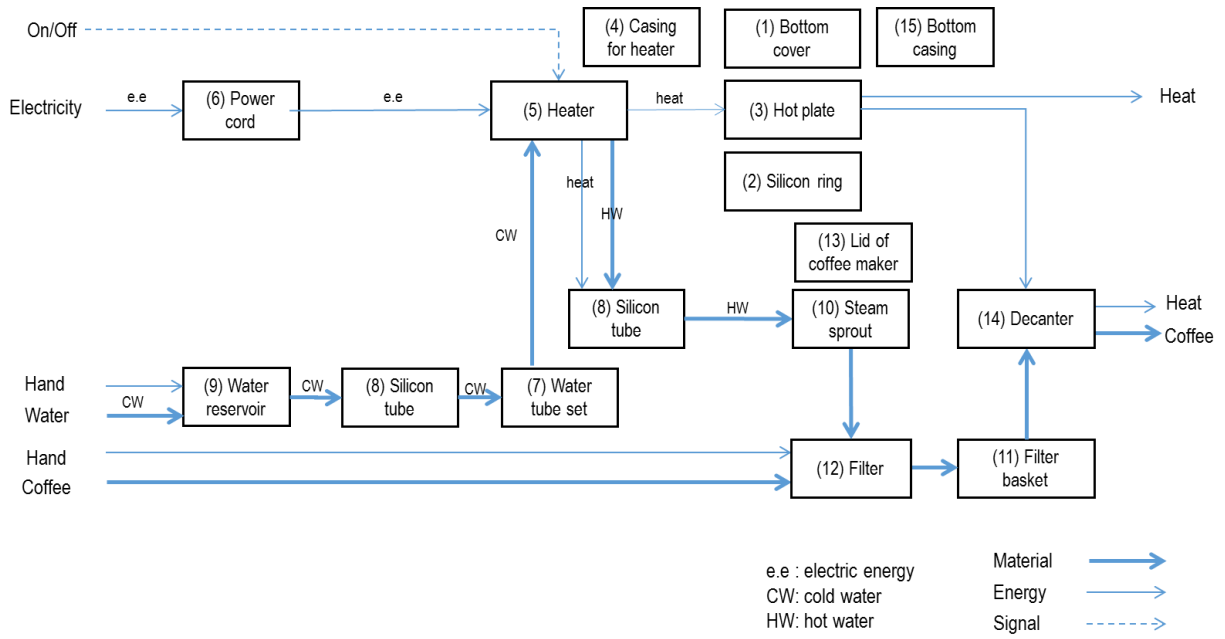


Figure 8 Functional diagram of the coffee maker

Module No.		1st			2nd			3rd					4th		5th	
		1	4	15	2	3	14	7	8	9	10	13	11	12	5	6
1	Bottom cover	1	1	1												
4	Casing for heater	1		1	1	1									1	
15	Bottom casing	1	1			1	1			1		1			1	1
2	Silicon ring		1			1										
3	Hot plate		1	1	1		1								1	
14	Decanter			1		1							1		1	
7	Water tube set								1							
8	Silicon tube							1		1	1				1	
9	Water reservoir			1					1		1	1	1			
10	Steam sprout								1	1		1	1			
13	Lid of coffee maker			1						1	1					
11	Filter basket						1			1	1			1	1	
12	Filter												1			
5	Heater		1	1		1	1		1							1
6	Power cord			1											1	

Figure 9 Modules of the coffee maker identified by DSM clustering algorithm

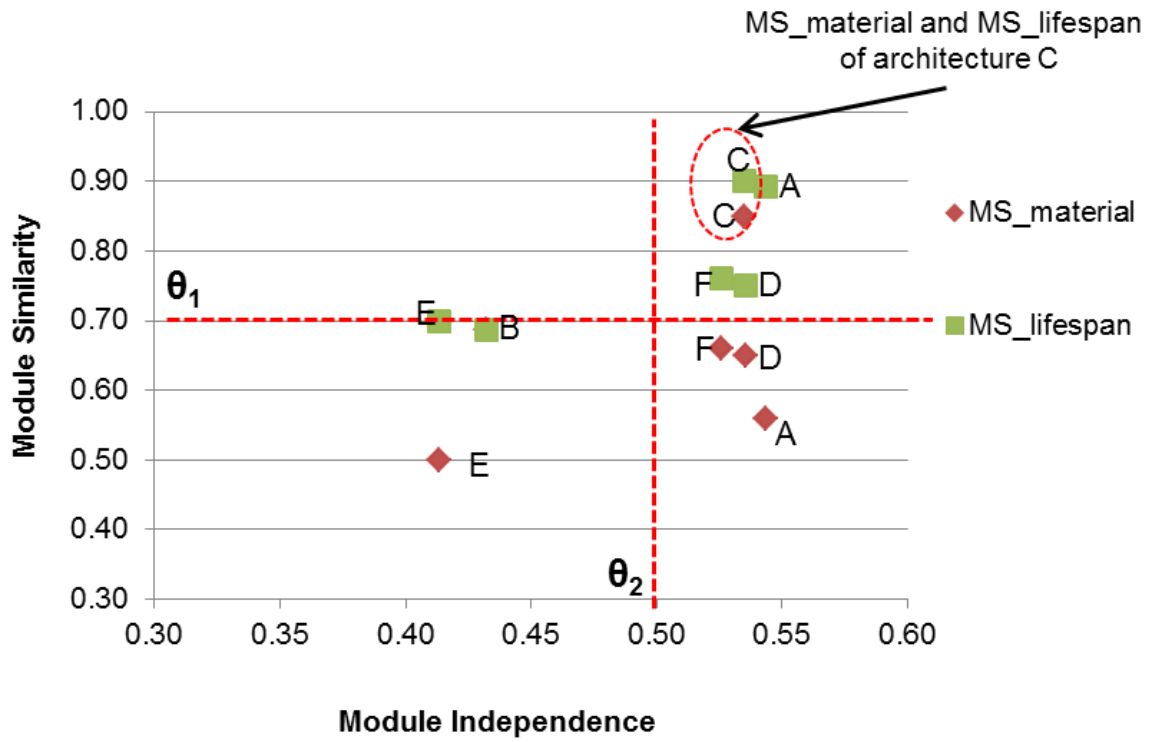


Figure 10 Categorized modular product architectures of the coffee maker in four regions according to the module independence and module similarity metrics

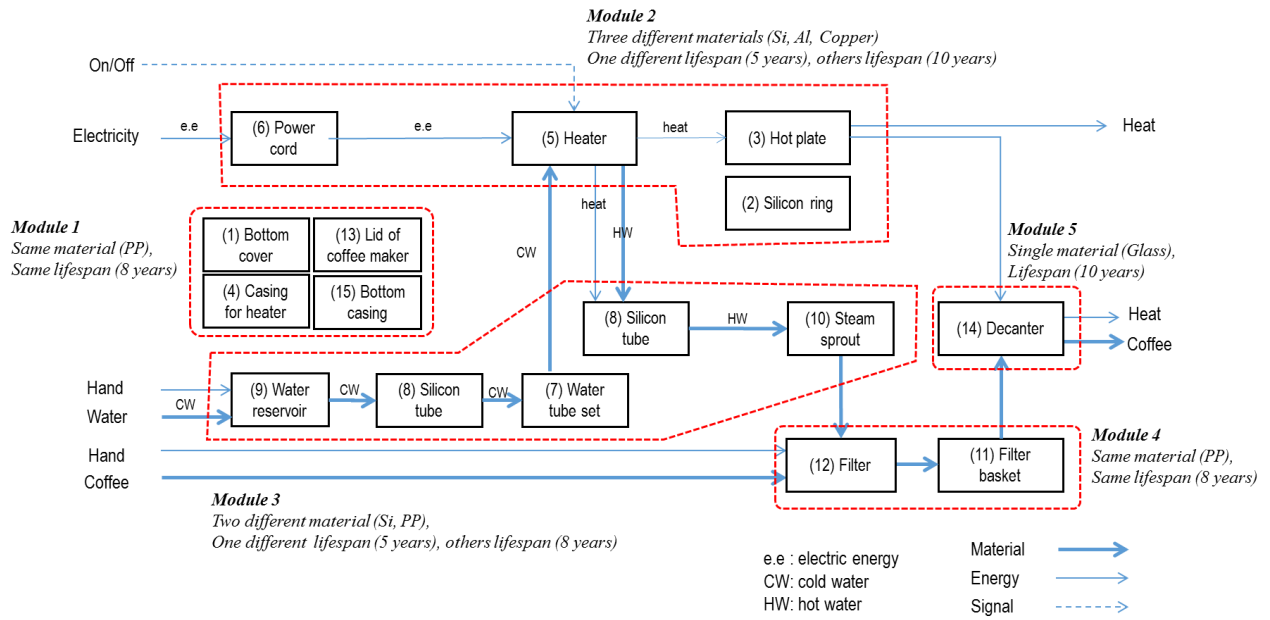


Figure 11 The eco-modular product architecture (C)